AN ANALYSIS OF THE MULTIVIBRATOR CIRCUIT

by

Harry Charles Freedman

A Thesis submitted for the Degree of

Master of Applied Science

in the Department

of

Electrical Engineering

THE UNIVERSITY OF BRITISH COLUMBIA

April 1938

de apled Dept of Meet

CONTENTS

Introd	\mathtt{uction}	Page 1.
(a)	The problem presented by the multivibrator circuit.	
(b)	The object of this investigation.	
Descrip	otion of the Multivibrator Circuit	2.
(a)	Essentials of a multivibrator Circuit.	
(b)	Occurrence of the multivibrator type of oscillation.	
(c)	Practical applications.	
The Ope	ration of a Multivibrator	3.
(a)	Qualitative analysis.	
(b)	Frequencies generated.	
(c)	Factors affecting frequency	
An Anal	ysis of the Multivibrator Circuit	6.
(a)	Assumptions for a practical solution.	
(b)	Solution of the equivalent network.	
Determi	nation of the Fundamental Frequency	10.
(a)	Solution of equations for the time constant.	
(b)	Comparison with Watanabe's results.	
(e)	An application of the theoretical results.	
(d)	Evalution of the correction factor.	
Experim	ental Check on Frequency Determination	14.
(a)	Apparatus and equipment employed	
(b)	Frequency measurement and technique.	
(c)	Experimental results.	
	(a) (b) Descrip (a) (b) The Ope (a) (c) An Anal (a) (b) Determi (a) (b) (c) (d) Experim (a) (b)	circuit. (b) The object of this investigation. Description of the Multivibrator Circuit (a) Essentials of a multivibrator Circuit. (b) Occurrence of the multivibrator type of oscillation. (c) Practical applications. The Operation of a Multivibrator (a) Qualitative analysis. (b) Frequencies generated. (c) Factors affecting frequency. An Analysis of the Multivibrator Circuit (a) Assumptions for a practical solution. (b) Solution of the equivalent network. Determination of the Fundamental Frequency (a) Solution of equations for the time constant. (b) Comparison with Watanabe's results. (c) An application of the theoretical results. (d) Evalution of the correction factor. Experimental Check on Frequency Determination (a) Apparatus and equipment employed. (b) Frequency measurement and technique.

	Page
VII Waveform Analysis	15.
(a) General approach.	
(b) The waveform of the voltage across the plate resistance.	
(c) The waveform of the voltage across the grid leak condenser.	÷
(d) The waveform of the voltage across the grid leak resistance.	≝
VIII Conclusions.	23.
IX Acknowledgement.	23.
X Appendices.	24.
XI Bibliography.	27.

AN ANALYSIS OF THE MULTIVIBRATOR CIRCUIT

Introduction

The multivibrator was first demonstrated by Abraham and Bloch in 1919. Since that time many attempts have been made to work out a satisfactory mathematical analysis of its operation. To quote E. B. Moullin "the multivibrator system does not lend itself to exact analysis or to an investigation by Fourier series". For example, van der Pol has obtained an expression for the conditions for maintenance of oscillations and he finds that the steady state is made possible by assuming residual induction in the system. Van der Pol sets up a second degree differential equation for which no exact mathematical solution is known (at present) to exist. Hund also sets up differential equations with which to explain the action of a multivibrator system but he makes no attempt to solve these equations. Perhaps one of the best papers on the multivibrator system is that of Watanabe, wherein he presents a theoretical discussion and graphical analysis of its operation. Later we shall compare our results with Watanabe's.

Moullin, E.B., "Radio Frequency Measurements", 1931. 3.

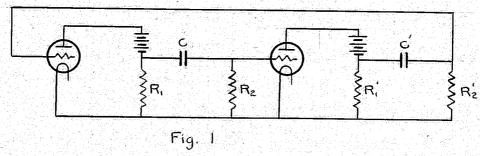
Abraham and Bloch, Ann. der Phys., vol. 12, p.237, 1919.

Van der Pol, B., I.R.E., vol.22, p.1051, 1934. Hund, A., "High Frequency Measurements". p.54, 1933. Watanabe, Y., I.R.E., vol.18, p.327, 1930. 4.

It is the purpose of this paper to try to give a workable analysis which will predict with some degree of accuracy the frequency and waveforms of the multivibrator circuit. The analysis presented will be verified, as far as possible, by actual experimental results.

The Multivibrator Circuit.

The multivibrator is essentially a two-stage resistance--coupled amplifier with the output of the second stage fed back into the grid of the first stage as shown in Fig. 1.



Oscillations of the multivibrator typewcan occuriin any audio-frequency amplifier employing a grid leak and a grid condenser, provided only that there is some connection between output and input by which the amplifier can supply its own input in the proper phase and in sufficient magnitude. Oscillations of this type occur in many audio-frequency amplifiers as a result of energy fed back through a common plate impedance. Such oscillations are frequently called "motor-boating" because their frequency is very low and is comparable to the sound of a motor-boat engine.

Multivibrators are chiefly used as a source of harmonics in the measurement of frequency.

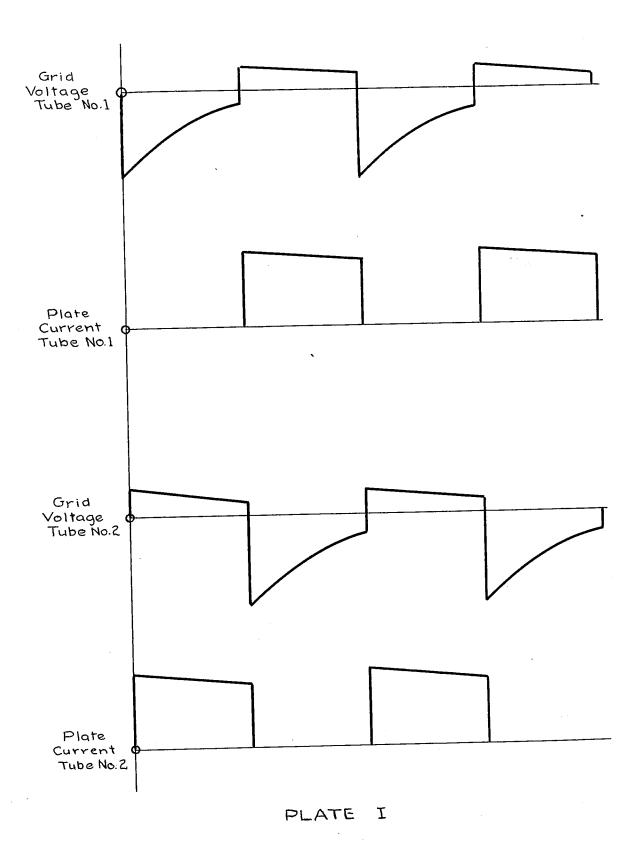
Harmonics as high as the 300th. can be detected in the output. The fundamental can be made an integral part of an injected control frequency, and thus a high degree of accuracy can be obtained in frequency measurements. The wave-form of the multivibrator is greatly distorted which restricts its use as a low frequency generator. It is, however, finding some use as a time base in oscilloscope circuits.

The Operation of a Multivibrator.

Since there is no resonant circuit (see Fig.1), the generated frequency of a multivibrator depends upon the time constants of the circuit. Such an arrangement will oscillate because each tube produces a phase shift of 180°. It may be noted here that van der Pol² treats multivibrators as a special case of "relaxation oscillators", that is oscillators which do not depend upon tuned circuits but only upon the time constants or "time of relaxation" of the circuits employed.

'The operation is started by a slightly positive voltage irregularity at the grid of tube No.1. This small voltage is amplified by the two tubes and then reapplied to the grid of tube No.1 in a very much enlarged form, to be again amplified and so. This action takes place almost instantly. The result of repeated amplification is to cause the grid of tube No.1 to

Dye, D.W., Phil. Trans. of Ro. Soc., Vol.224A, p.259,1923-4.
 Van der Pol, B., Phil. Mag., Vol.2, p.978, 1926.



(To face page 4.)

increased its potential suddenly and to make the grid potential of tube No.2 to decrease just as suddenly (i.e. become more negative). These considerations are shown ideally in Plate I. This rapid change is brought to a stop when the plate current of one of the tubes, in this case tube No.2, is cut off; for then all amplification ceases and for the moment one tube is drawing a heavy plate current while the other tube takes little or no plate current. This condition is unstable, because the leakage through the grid-leak resistances discharging the grid-leak condensers gradually brings the grid potentials back to normal. As the grid potential of tube No. 2 becomes less negative as a result of this grid-leak action, a point (cut-off) is reached where plate current in tube No. 2 will flow. Amplification is now possible and any minute irregularity that increases the grid voltage of tube No.2 will be amplified. This will build up a very sudden positive voltage on the grid of tube No. 2 while causing the grid of the first tube to go so negative that amplification is rendered impossible. From the above it can be seen that the tubes operate alternately, when one tube suddenly acquires a large positive grid potential, the other acquires a large negative grid potential.

In general, the frequency of the oscillations produced by the above action depends upon the rate at which the grid vol-

^{1.} Hull & Clapp, I.R.E., Vol. 17, p.252, 1929.

tages decay through the grid-leak resistances and condensers associated with each tube. Hence, the time to complete one cycle is made up of two parts, the time constants of each of the two grid-leak resistances and condensers. This frequency is given approximately by the formula

The above expression does not take into account the plate reresistances, the dynamic plate resistances or the amplification constants of the tubes.

There is little doubt that the frequency is influenced to some extent by the resistances in the plate circuit and by the characteristics of the tubes themselves. Dye' and others have observed errors as high as 25% between the actual observed frequency and the frequency as given by equation (1). Terman² states that "the frequency is determined primarily by the grid-leak resistance and grid condenser capacity, but it is also influenced by the remaining circuit constants, tube characteristics and electrode voltages". Later it will be shown in part the effect of some of these circuit constants upon the frequency of the multivibrator. The practical frequency range is from

^{1.} Dye, D.W., loc. cit.

^{2.} Terman, F.E., "Measurements in Radio Engineering", p.131, 1935.

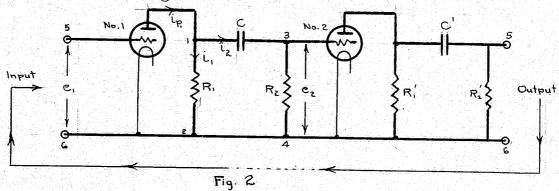
about 1 cycle per minute to 100,000 per second which is much the same as any audio-amplifier circuit.

Analysis of the Multivibrator Circuit.

In order to facilitate a practical solution, the follow-ing assumptions were made and are believed justifiable.

- 1. The circuit is a two-stage resistance--coupled amplifier with output coupled back to input.
- 2. Each tube produces a phase shift of 180°, causing the output of the second tube to supply an input to the first tube that is exactly the right phase to sustain oscillations.
- 3. The time constant of the oscillations generated is made up of the time constant of the first tube and its connecting network plus the time constant of the second tube and its associated network. These are not necessarily equal unless each circuit has the same parameters.
- 4. Straight line characteristics are assumed for triodes operated at normal voltages. This is equivalent to assuming "μ" and dynamic plate resistance constant.
- 5. Grid current can be neglected.
- 6. Any triode for practical purposes can be reduced to an equivalent network.
- 1. Colebrook, F.M., J.I.E.E., vol.67, p.157, 1929.

If only alternating current components are considered, for audio-frequencies the multivibrator circuit can be represented as in Fig. 2.



Where

R2 and R2 are grid leak resistances.

C and C' are grid condensers.

R, and R, are plate resistances.

For mathematical convenience assume that the circuit is symmetrical, hence $R_i = R_i'$, C = C', $R_z = R_z'$ and tube No.1= tube No.2.

Let

«e. = any instantaneous voltage applied to tube No.1

 ϵ_z = instantaneous voltage appearing across points 3 and 4

 i_R = the a.c. plate current of tube No.1

 $r_p =$ the dynamic plate resistance.

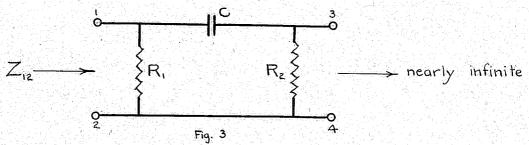
 μ = the amplification factor.

p = the Heaviside operator

Since it was assumed that any triode operated at normal voltages has essentially a straight line characteristic we have when tube No.1 is in operation

$$i_{P} = \frac{-\mu e_{1}}{r_{P} + Z_{12}} (1)$$
 (2)

where Z_{12} is the total impedance between points 1 and 2.

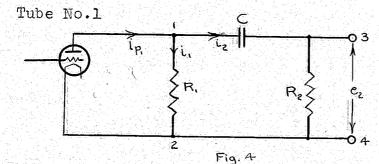


Hence Z_{12} is given by

$$Z_{12} = \frac{1}{\frac{1}{R_1} + \frac{1}{R_2 + \frac{1}{R_2}}}$$
 (3)

Simplifying

$$Z_{12} = \frac{(pCR_2 + 1)R_1}{pC(R_2 + R_1) + 1} V$$
 (4)



The plate current of tube No.1 divides into two branches as shown Fig.4, the "C"-branch carries current i_2 while the "R" -branch carries current i_1 . These currents can be expressed by

$$i_1 = \frac{R_z + \frac{1}{pC}}{R_1 + R_2 + \frac{1}{pC}} \cdot i_p, \tag{5}$$

and
$$i_2 = \frac{R_2}{R_1 + R_2 + \frac{1}{pC}}$$
 i_p (6)

Substituting equation (2) in equation (6)

$$i_2 = \frac{pCR_1}{pC(R_1 + R_2) + 1} \cdot \frac{-\mu e_1}{r_p + Z_{12}}$$
 (7)

The voltage across points 3 and 4 is given by ez or iz Rz

$$\therefore \ \varepsilon_z = i_z R_z$$

$$=\frac{-CR_{1}R_{2}\mu \cdot pe_{1}}{C(R_{1}r_{p}+R_{2}r_{p}+R_{1}R_{2})\left\{p+\frac{r_{p}+R_{1}}{C(R_{1}r_{p}+R_{2}r_{p}+R_{1}R_{2})}\right\}}$$
(8)

Let

$$K = \frac{\mu}{1 + \frac{\pi}{R_{1}} + \frac{\pi}{R_{1}}}$$
and
$$b = \frac{\tau_{p} + R_{1}}{C(R_{1}R_{2} + R_{1}\tau_{p} + R_{2}\tau_{p})}$$

$$(9)$$

$$=\frac{1}{CR_2\left\{1+\frac{R_1 r_P}{R_2(r_P+R_1)}\right\}}$$
(10)

Substituting equations (9) and (10) in equation (8) we have

$$e_z = -K.\frac{P}{P+D}.e_1$$
 (ii)

This equation represents the operational solution of the transient through tube No.1 and its associated network when any voltage e_i is applied to its grid. The voltage e_z is determined by the solution of equation (N). A similar equation is obtained for the transient through tube No.2 and its associated network when it becomes operative.

Determining the Fundamental Frequency.

From previous considerations the voltage e, applied to the grid at the beginning of each cycle reached its maximum value instantaneously through successive amplifications. In all respects e, has the form of a steady e.m.f. suddenly applied to a network at time zero (beginning of the cycle). These conditions are equivalent to Heavisides "unit function". For convenience let the maximum value of e, be E, Hence equation (II) becomes

$$e_2 = -K \cdot \frac{p}{p+b} \cdot E_1 \cdot 1. \tag{12}$$

The solution of which is

$$\epsilon_2 = -KE_1 \epsilon^{-bt}$$
 (13)

The time constant for tube No.1 and its associated network is determined by equation (13) which is an exponential function. Let T_1 be the time constant for this first portion of the cycle.

Hence

$$T_i = \frac{1}{b}$$

where

$$b = \frac{1}{CR_2 \left\{ 1 + \frac{R_1 r_p}{R_2 (R_1 + r_p)} \right\}}$$

$$T_1 = CR_2 \left\{ 1 + \frac{R_1 r_p}{R_2 (R_1 + r_p)} \right\}$$
(14)

A similar expression can be obtained for T_2 , the time constant which determines the second portion of the cycle. Since each tube functions alternately, T_2 must be evaluated by solving separately for the transient through tube No.2 and its associated network. Since it was assumed that the multivibrator has symmetrical circuits which is the usual case, the time constants for each portion of the cycle will be equal; i.e., T_1 equals T_2 .

Therefore the time constant for the complete cycle for symmetrical circuits is given by T where

$$T = T_1 + T_2$$

$$= 2CR_2 \left\{ 1 + \frac{R_1 r_p}{R_2 (R_1 + r_p)} \right\}$$
(15)

The frequency will, of course, be given by

$$f = \frac{1}{T}.$$

where

f = fundamental frequency in c.p.s.
T = time constant of a complete oscillation.

It might be well to compare equation (15) with the results from other sources. For example the equation usually given for a symmetrical multivibrator circuit is

$$T = 2 \cdot CR_2. \tag{17}$$

This equations differs from (15) by the factor $\{1+\frac{R_1r_2}{R_2(R_1+r_2)}\}$ Later we shall examine this correction factor more closely with the aid of graphs. Again Watanabe gives the following formula for a symmetrical circuit.

$$T = 2 CR_2 \log_{\epsilon} \frac{E_1 - e_c}{e_c}$$
 (18)

 E_i = the maximum value of e_i appearing on the grid.

e = the residual voltage retained by the condensers after discharge.

Unfortunately he does not state how this expression has been derived. The values of E, and ec or their ratios can be obtained from oscillograms. The expression given by Watanabe differs from (15) by the "correction" factor

$$\log_{\varepsilon} \frac{E_1 - e_c}{e_c} \tag{19}$$

In general E, is several times larger than ec, thus this correction factor is comparable to unity.

An examination of many papers on the frequencies of multivibrators bears out the fact that the actual observed time constant is always greater than the time constant as given by $T = 2 \cdot CR_2$. For example Dye² calculated the time constant of a symmetrical circuit using equation (17) and obtained a time constant of 930 x 10 seconds, but the observed time constant was actually 1000 x 10 seconds, where the circuit constants were $C = .0062 \mu f$, $R_1 = R_2 = 75 000$ and $r_p = 0.000 r_p = 0.000$ (estimated) 8000 ohms. Hence the calculated result would have

where

Watanabe, Y., "loc. cit".
 Dye, D.W., "loc. cit."

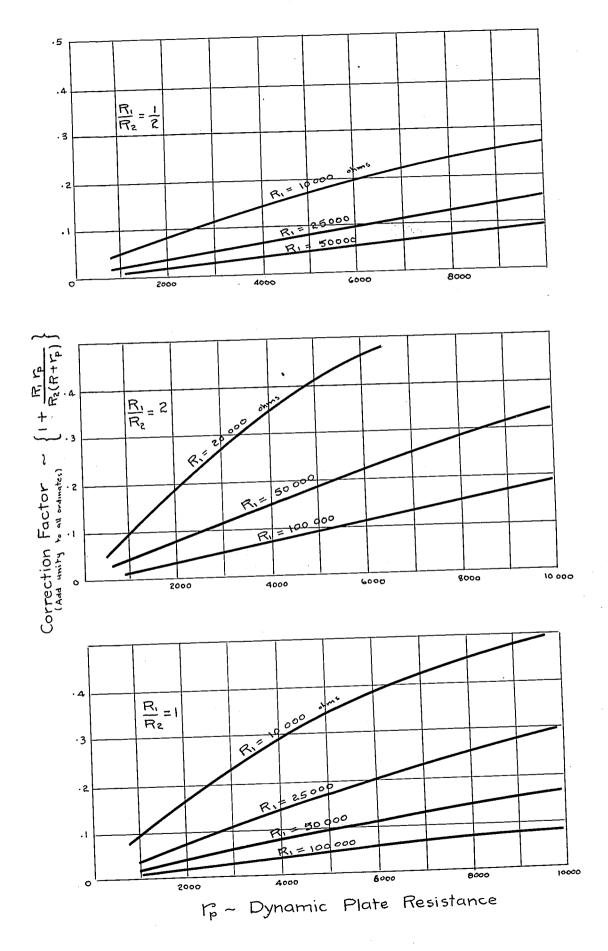


PLATE I

to be multiplied by a correction factor equal to 1.07 (approx.) to obtain the observed results. Using the correction factor as obtained from equation (15) we have for the above values

Correction factor =
$$1 + \frac{R_1 r_p}{R_2 (R_1 + r_p)}$$

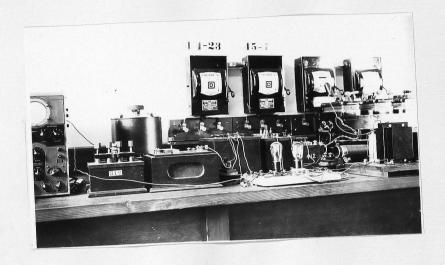
= $1 + \frac{75000 \times 8000}{75000 \times 83000}$
= 1.09

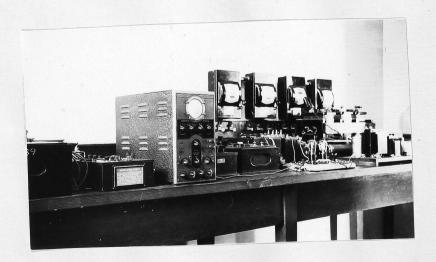
which compares favourably with the experimental result of 1.07. This would indicate that the correction factor as obtained from equation (15) in our analysis is of the right order and magnitude.

To get a clear idea of the magnitude of this correction factor as given by equation (15) namely,

$$\left\{1+\frac{R_1 P_0}{R_2(R_1+P_0)}\right\}$$

values were calculated for various circuit parameters and dynamic plate resistances. The results are shown by the graphs in Plate II. It can be seen that theoretically the error in the time constant can be as high as 50 per cent. In practice, however, these extreme values are never used. The graphs also show that for good results R_1 should be less than R_2 . This bears out Watanabe's assumption as stated in his analysis. It may also be noted that best operation, in so far as frequency prediction is concerned, should be obtained with tubes having low values of dynamic plate resistance, and R_1 and R_2 should at all times be much larger than the dynamic plate resistance.





Experimental Check on Frequency Determination.

An experimental symmetrical multivibrator was constructed using Leeds and Northrup precision resistances and condensers. The general layout is shown in Plate III. Many different types of triodes were tried such as 71-A's, 01-A's, 45's, 30's, 31's, 26's and 112-A's. Oscillograms were obtained by means of a cathode-ray oscilloscope.

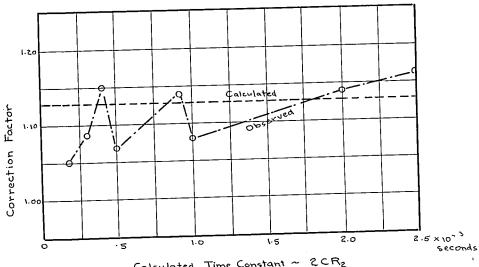
The frequency of the fundamental was determined by means of a modified Campbell bridge². This bridge gave sharp resonance points when used with a Moullin vacuum tube voltmeter. However the range was limited from about 400 c.p.s. to 6000 c.p.s.. To check the accuracy of the bridge an electrically driven tuning fork rated at 1000 c.p.s. was used. The results after several trials gave the mean frequency of the tuning fork as 994 c.p.s.

In the experiment tubes were operated at or near normal voltages. No attempt was made to measure dynamic plate resistances as it was felt that the manufactures tables would give values that were accurate enough for all practical purposes. Leads to the various pieces of apparatus were short and straight. The frequencies generated appeared to be stable with no indication of "drift". In fact once the oscilloscope was synchronized with the multivibrator no other adjustments were necessary.

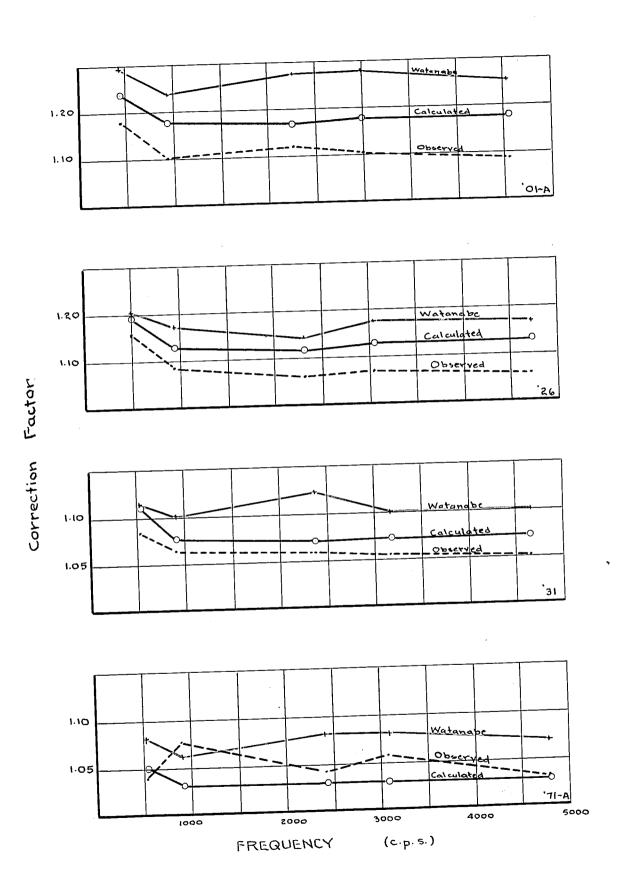
^{1.} Clough--Brengle Co.

^{2.} See Appendix "A".

C = C' T pf .025 .02	Calc'd Time Const. 2CR2 2.5 × 10-3	Obser'd Freq c.p.s	Obser'd Time Constant	Factor	Calc'd Correct. Factor
C = C' T pf .025 .02	Calc'd Time Const. 2CR2 2.5 × 10-3	Obser'd Freq c.p.s	Obser'd Time Constant	Obser'd Correction Factor	Calc'd Corvect. Factor
.02	1		1	i	1.13
.008	2.0 1.0 8 .5 .4 .3	370 920 1100 18 <i>5</i> 0 2180 30 <i>5</i> 0 4800	2.7 1.09 .91 .52 .46 .33 .21 Mean	1.14 1.09 1.14 1.07 1.15 1.09 1.05	1.13



Calculated Time Constant ~ 2 CR2 Fig. 4



Graphs to accompany Table II.

 1			1		i		Correction Factors		
Tube.	Ri ohms	R ₂	C ht.	2 CR2 × 10-3	065. Freq. c.p.s.	Obs. Time Constant × 10	Obserid	1+ R. rp R.(R.+ro)	Watamabe 1g Ei-Cc
	50000	50000	.01	1.0	910	1.1	1.10	1.17	1.24
35 V.	50000	35000	.025	1.75	485	2.0	1.18	1.24	1.29
۲ °	35000	50000	.004	.40	2320	.43	1.13	1.26	1.28
0001	50000	500 0 0	.003	•30	3020	.34	1.11	1.17	1.28
ب ۱۱	50000	50000°	.002	.20	4600	.218	1.09	1.17	1.25
	50000	50000	.01	1.0	920	1.09	1.09	1.13	1.17
135 V.	50000	35000	.025	1.75	491	2.1	1.16	1.19	1.20
2000	35000	50000	.004	•4	2350	.43	1.06	1.12	1.15
2007	50000	50000	.003	.3	3050	.33	1.09	1.13	1.18
10	50000	50000	.002	.2	4750	.21	1.05	1.13	1.17
	50000	50000	.01	1.0	940	1.06	1.07	1.08	1.10
35 V.	50000	35000	.025	1.75	555	1.8	1.08	1.11	1.11
-	35000	50000	.004	.4	2400	.42	1.06	1.07	1.12
31	50000	50000	.003	.3	3150	.32	3 1.0€	1.08	1.10
7.		50000	.002	.2	4710	.2]	1.05	1.08	1.10
71-A 19= 1820 ~ 135 V.	50000		.01	1.0	940	1.00	3 1.0	7 1.03	1.06
	; 	1	.025	1.75	540	1.8	5 1.04	1 1.05	1.08
	35000	}	.004	.4	2400	.4	2 1.0	4 1.03	3 1.08
	20		00.	3 .3	3100	.3	2 1.0	6 1.03	3 1.0
	u l	1	0 .00	2 .2	4800	0 .2	1 1.0	3 1.03	3 1.0

^{* &}quot;Technical Manual", Hygrade Sylvania Corp., 1937.

The results of a typical run for a symmetrical circuit using '26 tubes are shown in Fig.4. In this case, R, and R, were constant while the condensers (C) were varied together so as to cover the indicated frequency range.

A further type of check was decided upon in the form of a comparison between the correction factors as obtained from the following

- 1. Actual observed time constant 2 CR2
- 2. $1 + \frac{R_1 r_p}{R_2(R_1 + r_p)}$ calculated from circuit values.
- 3. Watanabe's factor $\log_{\epsilon} \frac{E_{i}-e_{c}}{e_{c}}$ which was obtained from oscillograms.

The results of the above using various tubes and circuit values in symmetrical circuit are shown in Table II. Some difficulty was experienced in evaluating Watanabe's correction factor from the oscillograms since ec is small compared to E. A slight error in measuring ec results a much larger error in the correction factor. On the whole the agreement is quite close.

Waveform Analysis.

In the following analysis only symmetrical multivibrator circuits are considered. Although the same reasoning can be applied to unsymmetrical circuits. It should also be noted that only the alternating components are treated, as the direct current components can easily be superimposed upon the others. The cathode-ray oscilloscope tracings show alternating com-

ponents only. These tracings were copied directly from the oscilloscope screen.

The Waveform of the Voltage Across the Plate Resitance R.

Consider the portion of the cycle during which tube No.1 is in operation and plate current ip. is flowing,

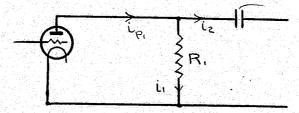


Fig. 5

from equation (2) we have

$$i_{p_i} = \frac{-\mu e_i}{r_p + Z_{12}}$$

and from equation (6)

$$i_1 = \frac{R_2 + \frac{1}{pC}}{R_1 + R_2 + \frac{1}{pC}} \cdot i_p$$

Substituting and simplifying in equation (6) we have

$$i_{1} = \frac{(pR_{2}C + 1) (-\mu e_{1})}{[pC(R_{1} + R_{2}) + 1] (r_{p} + Z_{12})}$$

$$= \frac{(pCR_{2} + 1) - \mu e_{1}}{r_{p}(pCR_{1} + pCR_{2} + 1) + pCR_{2}R_{1} + R_{1}}$$

$$= \frac{(pCR_{2} + 1)(-\mu e_{1})}{pC(R_{1}r_{p} + R_{2}r_{p} + R_{1}R_{2}) + r_{p} + R_{1}}. (20)$$

Let the instantaneous voltage across R, be given by e_{R_i}

$$= \frac{R_1(pCR_2+1)(-\mu e_1)}{C(R_1r_p+R_2r_p+R_1R_2)\{p+\frac{r_p+R_1}{C(R_1r_p+R_2r_p+R_1R_2)}\}}$$
(21)

Since

$$b = \frac{\Gamma_{1} + \Gamma_{1}}{C(R_{1}\Gamma_{1} + R_{2}\Gamma_{1} + \Gamma_{1}R_{2})}$$
and $K = \frac{P}{(1 + \frac{\Gamma_{1}}{R_{1}} + \frac{\Gamma_{2}}{R_{2}})}$

$$\vdots \quad e_{R_{1}} = \frac{(PCR_{2} + I)(-PE_{1})}{CR_{2}(1 + \frac{\Gamma_{2}}{R_{1}} + \frac{\Gamma_{2}}{R_{2}})(P + b)}$$

$$= \frac{-K(P + \frac{1}{CR_{2}})}{(P + b)} \cdot e_{1}$$
(22)

Let
$$\frac{1}{CR_z} = \alpha$$

$$\therefore e_{R_z} = \frac{-K(p+\alpha)}{p+b} \cdot e_z \qquad (23)$$

The solution of equation (23) for the first portion of the cycle during which e, takes the form of steady e.m.f. suddenly applied with a maximum value of E, is

$$\epsilon_{R_i} = -E_i K \frac{P+\alpha}{P+D} \cdot 1$$

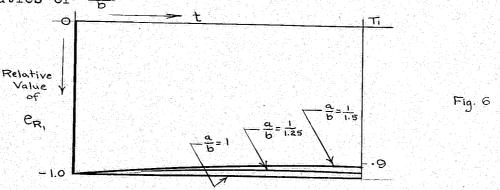
$$= -E_i K \left[\frac{\alpha}{b} + \varepsilon^{-bt} (1-\frac{\alpha}{b}) \right] \qquad (24)$$

From previous considerations

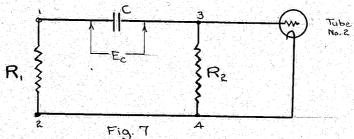
$$\frac{a}{b} = \frac{CR_2}{CR_2\left\{1 + \frac{R_1 \cdot \Gamma_0}{R_2\left(R_1 + \Gamma_0\right)}\right\}}$$

$$= \frac{1}{1 + \frac{R_1 \cdot \Gamma_0}{R_2\left(R_1 + \Gamma_0\right)}} < 1$$

An examination of equation (24) is shown in Fig. 6 for various ratios of $\frac{2}{5}$.



During the second portion of the cycle no plate current of the in Tube No.1, hence the voltage appearing across R, is directly dependent upon the discharge of the condenser in the circuit of tube No. 1.



This circuit is represented in Fig. 7.

Let

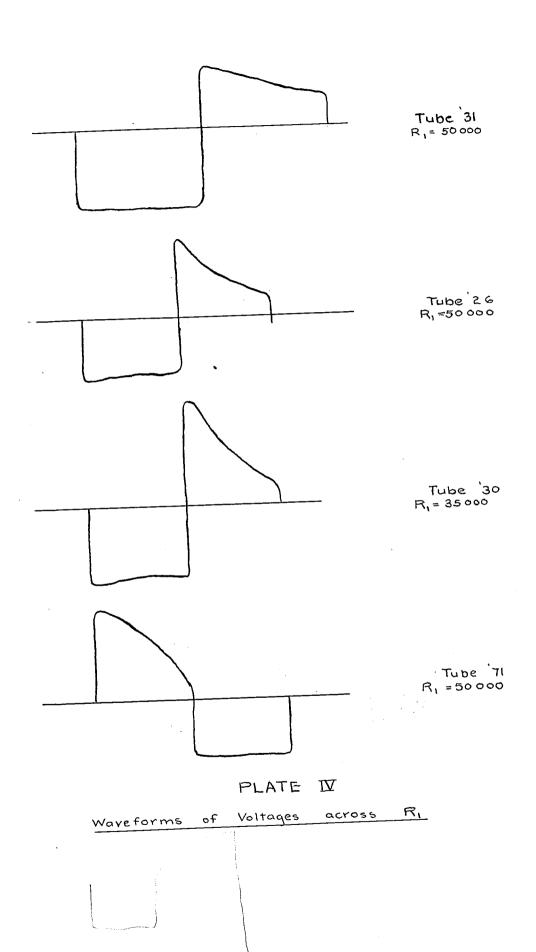
 $e_{R} =$ instantaneous voltage across R, during this portion of the cycle.

 $E_c = maximum \ voltage \ on \ the \ C$.

ic = instantaneous current due to co

Therefore

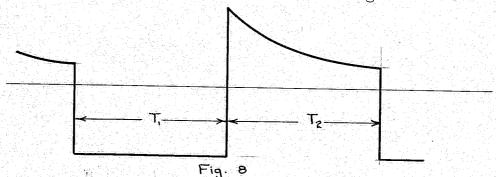
$$\begin{array}{lll}
e_{R}^{i} &= & i_{c} R_{1} \\
&= & \frac{E_{c}}{R_{1} + R_{2} + \frac{1}{P_{c}}} R_{1} & 1 \\
&= & E_{c} \frac{R_{1}}{R_{1} + R_{2}} \frac{P}{\{p + \frac{1}{CR_{1} + CR_{2}}\}} 1, & (25)
\end{array}$$



which has as a solution

$$e_{R}^{\dagger} = E_{c} \frac{R_{1}}{R_{1} + R_{2}} \cdot \mathcal{E}^{-\frac{t}{CR_{1} + CR_{2}}}$$
(26)

This equation is an exponential. Combining this equation with equation (24), the waveform of the a.c voltages appearing across R, can be ideally represented as in Fig.8.



From this we should expect a rectangular waveform during T_{i} and an exponential during T_{i} . The oscillograms shown in Plate IV correspond closely with the theoretical waveforms.

The Waveform of the Voltage across Condenser C.

During the first portion of the cycle, plate current is flowing in tube No.1, therefore the voltage across condenser C will be given by

$$\begin{array}{c|c}
\vdots \\
R_1 \\
\downarrow R_2 \\
\downarrow i_1 \\
\hline
Fig. 9
\end{array}$$

$$\begin{array}{c}
e_c = \frac{1}{p^C} \cdot \frac{R_1}{R_1 + R_2 + \frac{1}{p^C}} \cdot i_{R_1} \cdot 1. \quad (27)
\end{array}$$

$$ip = \frac{-\mu e_1}{F_0 + Z_{12}} \left(1\right)$$

Substituting and simplifying equation (27)

$$\frac{F_{c}}{F_{c}} = -\frac{R_{1}}{P_{c}(R_{1}+R_{2})+1} \frac{\mu e_{1}}{r_{p}+Z_{12}}$$

$$= -\frac{\mu R_{1}}{P_{c}(R_{1}R_{2}+R_{1}r_{p}+R_{2}r_{p})+r_{p}+R_{1}} e_{1}$$

$$= \frac{-\kappa}{CR_{2}(p+b)} \cdot e_{1} \cdot 1. \quad (28)$$

Where k and b have the same meaning as given previously in equations (9) and (10) namely

$$k = \frac{\nu}{1 + \frac{\gamma_0}{R} + \frac{\gamma_0}{R}}$$

and b =
$$\frac{1}{CR_2\left\{1 + \frac{R_1 r_p}{R_2(r_p + R_1)}\right\}}$$

Equation (28) has for a solution during the first portion of the cycle

$$\epsilon_{c} = -\frac{E_{1}K}{CR_{2}b}(1 - \epsilon^{-bt})$$
(29)

where E, as before is maximum value of e,.

If $CR_{i} = \frac{1}{\alpha}$ then equation (29) becomes

$$\epsilon_{c} = -E_{1}K \frac{a}{b}(1 - \epsilon^{-bt}). \tag{30}$$

The form of this equation for various ratios of $\frac{\alpha}{6}$ is shown in Fig. 10.

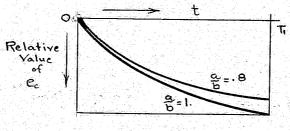


Fig. 10

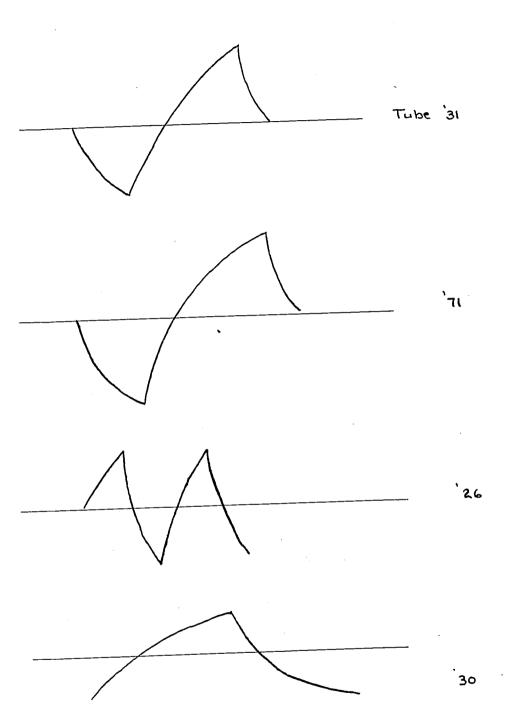
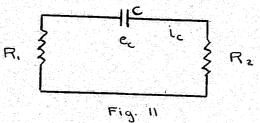


PLATE V.

During the second portion of the cycle, no plate current flows in tube No.1, thus the condenser C discharges.



Let

 $\epsilon_{c}^{'}=$ the instantaneous value of the e.m.f. across C .

E = Maximum value of e at the beginning of this portion of the cycle.

 i_c = the instantaneous current due to e_c .

Hence

$$e_c^1 = -\frac{i_c}{pC}$$
 1

but

$$\dot{l}_c = \frac{-E_c}{R_1 + R_2 + \frac{1}{pC}} \quad 1$$

:.
$$e'_{c} = \frac{-E_{c}}{pC(R_{1}+R_{2})+1}$$

(31)

which has for a solution

$$e'_{c} = -E_{c} e^{-\frac{t}{CR} + CR_{L}}$$
(32)

The graph of this equation (32) is an exponential which is to be expected. The combined waveform for the whole cycle is shown ideally in Fig. 12.

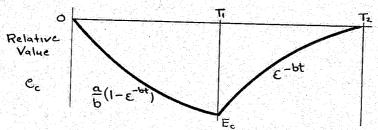
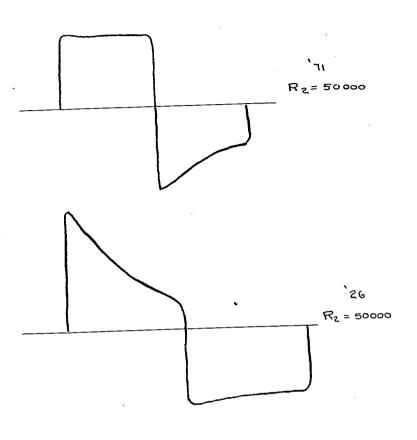


Fig. 12.



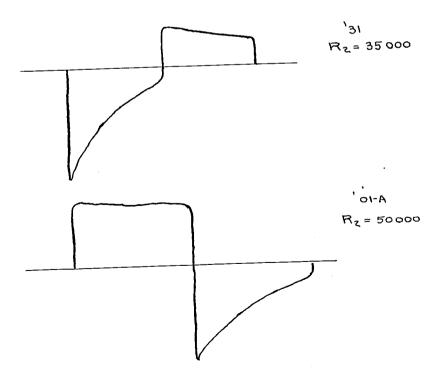


PLATE VI.

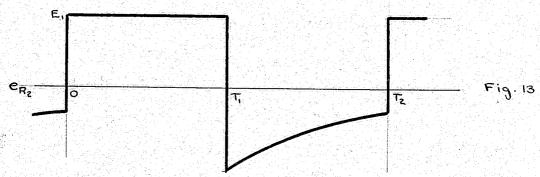
Again the oscillograms shown in Plate V can be compared with Fig. 12.

The Voltage Waveforms across the Grid Resistance R2.

The final waveform to be discussed is that appearing accross the grid-leak resistance (R_2) . From previous discussions it was shown that this voltage has essentially a rectangular form. However the voltage during the second portion of the cycle for the circuit of tube No. 1 will be determined by the condenser discharge and will be given by

$$e_{R_2} = E_c \frac{R_2}{R_1 + R_2} e^{-\frac{t}{CR_2 + CR_1}}$$
(32)

which is easily obtained from equation (26). The complete waveform is shown ideally in Fig. 13.



The oscilloscope tracings are shown in Plate VI. It will be noted that the actual waveform is closely rectangular during T_i , while during T_2 the waveform did not appear to follow the exponential form quite as closely for low values of R_2 .

Conclusions.

Unfortunately, the limitations of available apparatus prevented a full investigation of the multivibrator through wide ranges of frequency and circuit parameters. The results obtained from this study may be summarized as follows:

- 1. The frequency can be predicted with a fair degree of accuracy from the circuit parameters.
- 2. The waveforms as observed are accounted for theoretically and show close agreement with the predicted forms.
- 3. The effect of varing the plate voltage was not studied quantitatively but in general the frequency decrease in plate voltage.
- 4. There is field for further study in unsymmetrical circuits and also "multivibrator" types of oscillations appearing in single tetrode circuits.

Acknowledgements

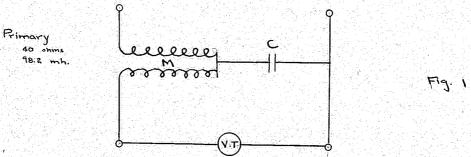
The writer wishes to thank Dr. H.J. MacLeod for his many helpful suggestions and for the priviledge of using the Electrical laboratory. Thanks are also due to Prof. W.B. Coulthard for examining many of the mathematical equations and G.I. Goumeniouk for the loan of much equipment from the Physics Department.

^{1.} See Appendix B.

Appendix A

Campbell Frequency Bridge

The circuit arrangement for this bridge is shown in Fig.1



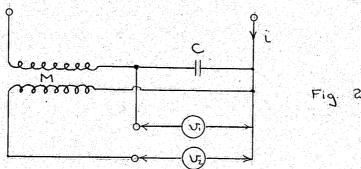
where M is a Campbell variable mutual inductance standard which has a range from -30 to +110000 microhenries and C is a standard air condenser.

The method is quick and results obtained are accurate. The resonance point is sharp and easily found. At balance the frequency is given by the following

$$w^{z} = \frac{1}{MC}$$

$$f = \frac{1}{2\pi \sqrt{MC}} = \frac{159200}{\sqrt{M_{H} \cdot C_{H}}} \quad \text{c.p.s.}$$

A further modification of the above is shown in Fig. 2.



1. Moullin, "loc. cit."

The frequency is obtained as follows

The condenser C in Fig.2 may be replaced by a pure resistance R and hence the frequency will be given by

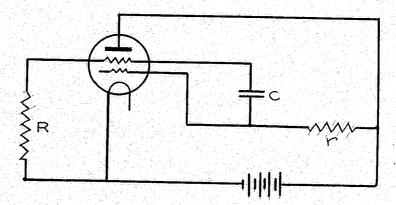
$$f = \frac{v_L R}{2\pi v_I M} c.p.s.$$

The impedance introduced into the multivibrator circuit by any of the above bridge circuits is small at the frequencies measured. Errors caused by harmonics can be neglected as given in an analysis by Moullin and others.

^{1.} Hund, A., High Frequency Measurements, p. 209, McG.-Hill, 1933.

Appendix B

Oscillations similar to those of a multivibrator can be produced by a single tetrode in a resistance-capacitance circuit, such as illustrated below



The time constant of the oscillations produced is given by

$$T = CR. (approx.)$$

Bibliography

Abraham, H. and Bloch, E., Ann. der Phys.,

表情:

vol. 12 p.237, 1919. --I.R.E. vol. 13, p.207, 1925. --Compt. rend., 168, p.1105, 1919.

Appleton, E.V., "Solution of the Representive Differential Equation of a Triode Oscillator",

Phil. Mag., vol.45, p.40, 1923.

- Berg, E.J., "Heaviside's Operational Calculus", McGraw-Hill, 1929.
- Bush, V., "Operational Circuit Analysis", John Wiley & Son, 1929.
- Colebrook, F.M., "Analysis of Triode Valve Equivalent Network"
 J.I.E.E., vol.67, p.157, 1929.
- Dye, D.W., "A Self-contained Standard Harmonic Wave-meter",
 Phil. Trans. Ro. Soc., London, vol. 224A,
 p. 259, 1923-4.
- Eastman, A.V., "Fundamentalsoof Vacuum Tubes", McGraw-Hill, 1937.
- Everitt, W.L., "Communication Engineering", McGraw-Hill, 1932.
- Glasgow, R.S., "Principles of Radio Engineering", McGraw-Hill, 1936.
- Hull, L.M. & Clapp, J.K., "A Convenient Method of Referring Secondary Frequency Standard Time Interval", I.R.E., vol. 17, p.252, 1929.
- Hund, A., "High Frequency Measurements", McGraw-Hill, 1933.

Moullin, E.B., "Radio Frequency Measurements",

C. Griffin & Co., London, 1931.

Peters, L.J., "Thermionic Vacuum Tube Circuits", McGraw-Hill, 1927.

Prince, D.C. and Vogdes, F.B., "Vacuum Tubes as Oscillation Generators",

G.E. Rev. 31, p.147, 1928.

Terman, F.E., "Measurements in Radio Engineering",

p. 129, McGraw-Hill, 1935.

van der Pol, B., "Relaxation Oscillations",

Phil. Mag., vol.2, p.978, 1926.
--"Non-linear Theory of Electric Oscillations", I.R.E., vol.22, p.1051, 1934.

Vigoureux, P. & Webb, C.E., "Principles of Electric and Magnetic Measurements", p.209,

Prentice-Hall, Inc., 1936.

Watanabe, Y., "Some remarks on the multivibrator",
I.R.E., vol, 18, p.327, 1930.