## AN APPROACH TO THE ORGANIZATION OF TAXONOMIES

# A THESIS SUBMITTED IN PARTIAL FULFILMENT OF THE REQUIREMENTS FOR THE DEGREE OF MASTER OF SCIENCE 

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#### Abstract

The ISA hierarchy used by present day inferential database systems is deficient in that it does not represent a variety of domain relationships (type relationships). Such hierarchies associate explicitly defined sets with the leaves of a tree. Non-leaf nodes in the tree inherit members from their child nodes. In keeping with the use of sets, this paper gives motivation for having type relationships other than subset. Included are union, intersection and a disjointness condition.


A formalism for the typed database (TDB) is given, using the monadic first order predicate calculus as its theoretical basis. Non-unit formulae represent intensional (general) information about the world being represented and unit ground clauses represent extensional (specific) information. Predicates represent types, and constant symbols represent set members. This is connected to the set concept via predicate extensions. The extension is that set of constant symbols which are provable as arguments to the given predicate.

Given the so-called concreteness condition and consistency of the TDB, the desired set theoretic relationships (union, intersection and disjointness) of predicate extensions follow. This strengthens the link between the formalism of the predicate calculus and the more natural set representation.

A canonical form of a TDB is shown that admits an appropriate machine representation. Using this is can be determined if a constant symbol as an
argument to a given predicate is provable (domain membership) in constant time. An update algorithm is developed and is shown to be correct in that it maintains concreteness and consistency. Thus the TDB is shown to be a practical generalization of the ISA hierarchy but is considerably more expressive.
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Section A Introduction

In recent works on relational database systems, especially as they arise in artificial intelligence, the need for a database of domains (using Codd's definition of Domain ${ }^{[3]}$ ) has become apparent. In simple data processing applications, the acceptance or rejection of data in a domain is based on a decision procedure for that domain such as correct alpha/numeric form or membership in a predefined set. This makes the primary assumption that each domain is independant of all others. This may be realistic for domains in which each entry of one domain is more or less unrelated to other domains (like numeric ones). However, work in artificial intelligence and inferential database systems acknowledges the dependancies amoung domains. Winograd led the way by using an ISA hierarchy to relate domains of objects and their properties. eg. a MOVEABLE-OBJECT ISA PHYSICAL-OBJECT ${ }^{[15] .}$

McSkimin and Minker formalize the ISA hierarchy by defining a semantic graph as a labelled tree in which the root node is the universal category (domain) and the leaves are primitive categories $7,8,9]$. In their formalism the elements, which are associated with the primitive categories, are inherited by the parent categories. As can be seen in their examples these trees tend to be "leafy" with many categories, some with unnatural names (such as non/human/male/mam). There is much duplication of category names but no mechanism is given for insuring that duplicate categories contain the same elements.

Also, McSkimin and Minker define a partitioning (disjointness condition between categories) without defining an update algorithm that will maintain the partition. In short, though they define the ISA heirarchy, they do not include a mechanism for enforcing data consistency.

Reiter has adopted the idea of a typed database formalized in the monadic predicate calculus $[10,11]$. He replaces the idea of an element being a member of a domain with the proof theoretic notion of provability. Here the domain is a monadic predicate in which the element is its argument. The structure, mathematics and algorithms for this typed database are beyond the scope of his paper.

It is the purpose of this paper to propose a structure for Reiter's typed database and develop the necessary mathematics and algorithms.

A domain in Codd's terminology will hereafter be referred to as a TYPE. An element will be referred to as an INSTANCE. For example, HUMAN is a TYPE for which JOHN is an INSTANCE. JOHN is said to have the property HUMAN. A type database (TDB) is then a logical theory in which groups of TYPEs (and hence INSTANCES) satisfy certain mathematical relationships called type relationships.

In order for $a \operatorname{TDB}$ to be practical it must satisfy certain conditions:

1) It must be descriptively rich, capturing type relationships other than simple set containment.
2) It must be structured so as to encourage only the most natural information content.
3) It must admit algorithms that are computationally efficient in both time and space.
4) It must admit updates in such a way as to prevent a user from violating a type relationship. (ie. enforce integrity constraints)

Section B motivates the inclusion of type relationships other than set containment. Section $C$ then defines a TDB. Condition 2 is addressed in section $C$ which defines an acyclic TDB and introduces a graphic notation. Structuring is completed in section $D$ by imposing the so-called concreteness condition on TDBs. With this and consistency all the desired set theoretic properties of the TDB follow. Section $E$ is devoted to an algorithm for reducing a given TDB to one which is efficient in both time and space. The final section details an update algorithm which ensures that concreteness and consistency of the TDB are maintained during updates.

To see why a more robust set of type relationships than simple set containment is important consider the following statements:

1) JANE is a WOMAN; hence JANE is a FEMALE (ISA)
2) JANE is a FEMALE; hence JANE is a WOMAN or JANE is a GIRL (but not both)
3) a) JOHN is a BACHELOR; hence JOHN is a MAN (ISA) b) JOHN is a BACHELOR; hence JOHN is SINGLE (ISA)
4) JOHN is a MAN and JOHN is SINGLE; hence JOHN is a BACHELOR

Statements 3 a and 3 b bear a resemblance to statement 1 in that both display set containment. However, in view of statements 2 and 4 we see that somehow FEMALE is composed of WOMAN and GIRL - WOMAN and GIRL being dis joint TYPEs. In contrast MAN and SINGLE intersect to give BACHELOR. The standard ISA hierarchy does not provide the formal equivalent of statements 2 and 4.

An inference of type 2 is important in that we would not want JANE to have the property FEMALE without her having one of the properties WOMAN or GIRL. Similarly we would not want JANE to have both the properties WOMAN and GIRL. As seen in the following sections, "concreteness" satisfies the former condition, consistency the latter.

The type relationship of type 4 is important when we want to define a TYPE as having INSTANCES which are common to a set of TYPEs. In an airline reservation system JOHN might have the properties NON-SMOKING, COACH,

MOVIE-WATCHING and 747 from which the system could infer that JOHN is a member of CABIN-B.

The way the above statements pair suggests the need for only two classes of type relationships:
A) The TYPE FEMALE is equivalent to the disjoint union of the TYPEs WOMAN and GIRL
B) The TYPE BACHELOR is equivalent to the intersection of the TYPEs MAN and SINGLE

The union in $A$ need not be disjoint, for example:
C) The TYPE PEOPLE is equivalent to the union of the TYPEs LEFT-HANDED and RIGHT-HANDED (allowing for the ambidextrous)

Graphically these are represented as:
A)
B)
C)



Set theoretically these can be represented as:
A) FEMALE $=$ WOMAN $\oplus$ GIRL
B) BACHELOR $=$ MAN $\cap$ SINGLE
C) PEOPLE = RIGHT-HANDED U LEFT-HANDED

In the graphical representation, the more restricted TYPE is drawn below the TYPE of which it is a subset. The four original statements can now be written in terms of sets:

1) JANE $\varepsilon$ WOMAN implies JANE $\varepsilon$ FEMALE
2) JANE $\varepsilon$ FEMALE implies JANE $\varepsilon$ WOMAN $\oplus$ GIRL
3) JOHN $\varepsilon$ BACHELOR implies JOHN $\varepsilon$ MAN $\cap$ SINGLE
4) JOHN $\varepsilon$ MAN $\cap$ SINGLE implies JOHN $\varepsilon$ BACHELOR

Section C Formal Preliminaries

The set notation of the previous section is convenient for visualizing the TYPE relationships. The first order predicate calculus, however, offers a well developed proof theory $[2,13]$. For this reason we shall develop our results within a first order framework. Refer to appendix $A$ for the interpretation given to special symbols used in what follows.

Definition TYPE Database (TDB)
A TDB is a 4-tuple (C, P, I, E) satisfying:

1) C is a finite set of constants.
2) $P$ is a finite set of unary predicate signs, called TYPES.
3) E is a finite set of atomic formulae of the form $P c$ where $\mathrm{P} \in \mathrm{P}$ and $\subset \boldsymbol{\varepsilon} \mathrm{C}$.
$E$ is called the extension of the TDB.
4) I is a finite set of well formed formulae of the form:
i) ( $x$ ) $P x \equiv P_{1} x \wedge P_{2} x \wedge \ldots P_{n} x$ or
ii) ( $x$ ) $P x \neq P_{1} x \vee P_{2} x$ v ... $P_{n} x$ where $\left[P, P_{1}, P_{2}, \ldots P_{n}\right] \subset P$.

In the event that $I$ contains a formula of the form (ii), it may also contain all of the formulae:
iii) ( $x) \sim\left(P_{i} x \wedge P_{j} x\right)$ for each $l \ll i<j \ll n$.

In which case the formula (ii) is said to be exclusive.
I is called the intension of the TDB.

## For Example:

(C, P, I, E) is a TDB where:
$C=[$ john, mary]
(INSTANCES)
$\mathbf{P}=$ [FEMALE, WOMAN, GIRL, MAN, SINGLE, BACHELOR] (TYPES)
$I=[(x)$ BACHELOR $x \equiv$ MAN $x \wedge$ SINGLE $x$,
( $x$ ) FEMALE $x$ WOMAN $x$ v GIRL $x$, $(x) \sim($ WOMAN $x \wedge$ GIRL $x)$ ]
(intension)
$E=[$ WOMAN mary, MAN john, SINGLE john]
(extension)

## Notation:

1) For brevity, the variable ' $x$ ' will be dropped where understood.
2) ( $C, P, I, E)$ will be referred to as T's constants, predicates, intension and extension where clarification is required.
3) Members of $C$ will be written in lower case, members of $\mathbf{P}$ in upper case.
4) For reasons of notational convenience we sometimes write $W \in I$ where $W$ is actually a clause ${ }^{[13]}$.
5) A TDB will be said to be consistent whenever I $U$ E is.
6) When we write $T \vdash W$ we will mean $I U E F W$ for any formula $W$.
7) $R(U, V)$ will refer to the resolvents $[13]$ of the formulae $U$ and $V$.

With this definition of a TDB we can replace the notion of an INSTANCE being a member of a TYPE (john $\varepsilon$ BACHELOR) with the predicate calculus notion of provability (I U E - BACHELOR john). However, we would still like to view a type as a set with certain set theoretic relationships.

The extension of $P \varepsilon P$ written $\|P\|_{T}$ is defined:

$$
\|P\|_{T} \equiv\left[\begin{array}{c|c|}
c & \quad \varepsilon \quad c, \quad I U E \vdash P c]
\end{array}\right.
$$

The subscript on $\|P\|_{T}$ will be dropped where implicit. Hence we can write c $\varepsilon\|\mathrm{P}\|$ for $\mathrm{T} \mid \mathrm{Pc}$. The set theoretic relationships between extensions of the last section do not automatically follow. We will give conditions under which each of the relationships given do follow.

Acyclicity of a TDB
The idea of a TYPE viewed as an ISA hierarchy is firmly related to the ideas of generalization and restriction. Logically we would like to think of one type containing another (ie. $\|P\| \subset\|Q\|$ ). This leads to the notion of a hierarchy of TYPES, motivating the following acyclicity definition ${ }^{[6]}$.

Definitions ALPHA, BETA and TAU
The relations $A L P H A_{T}$, BETA $_{T}$ and TAU $_{T}$ are defined on a TDB, $T$, over P x P:

$$
\begin{aligned}
& \text { 1) } P A L P H A_{T} Q \text { iff } Q \equiv P_{1} \vee P_{2} v \ldots P_{n} \varepsilon I \text { such that } \\
& \mathrm{P}=\mathrm{P}_{\mathrm{i}} \text { for some } \mathrm{i}, \mathrm{l}<=\mathrm{i}<=\mathrm{n} \\
& \text { 2) } P \text { BETA }_{T} Q \text { iff } P \equiv Q_{1} \wedge Q_{2} \wedge \ldots Q_{n} \varepsilon I \text { such that } \\
& Q=Q_{i} \text { for some } i, l<=i<=n \\
& \text { 3) } \mathrm{TAU}_{\mathrm{T}} \equiv \mathrm{ALPHA}_{\mathrm{T}} \mathrm{U} \mathrm{BETA}_{\mathrm{T}}
\end{aligned}
$$

The subscripts on ALPHA $_{T}$, BETA $_{T}$ and $T A U_{T}$ will be dropped where implicit. $A$ TDB is said to be acyclic iff $T A U^{+}$is irreflexive. ie.

$$
\begin{array}{r}
P_{0} \text { TAU } P_{1} \text { and } P_{1} \text { TAU } P_{2} \text { and } \ldots P_{n-1} \text { TAU } P_{n} \\
\text { implies not } P_{n} \text { TAU } P_{0} \quad(n>0)
\end{array}
$$

The graphical representation of Section $B$ can be adopted with

representing ( x$) \mathrm{Px} \equiv \mathrm{P}_{1} \mathrm{x} \wedge \mathrm{P}_{2} \mathrm{x} \wedge \ldots \mathrm{P}_{\mathrm{n}} \mathrm{x}(4 i)$ and with

representing ( $x$ ) $P x \equiv P_{1} x \vee P_{2} x \vee \ldots P_{n} x$ (4ii) and finally

representing ( $x$ ) $P x \equiv P_{1} x \vee P_{2} x \vee \ldots P_{n} x,(x) \sim\left(P_{i} x \wedge P_{j} x\right)$ (4ii and 4iii). Diagram C.l gives an example of this graphical representation of 1.

By convention, if $P$ TAU $Q$ then $P$ is directly below $Q$ in the graph. Thus a TDB is acyclic when and only when its graph is acyclic. Throughout this paper the acyclicity of all TDBs is assumed.

The following lemma gives us the property of set containment desired:


Lemma C. 1 Generalization
If $T$ is a TDB, [ $\mathrm{P}, \mathrm{Q}] \subset \mathrm{P}$ and $\mathrm{P} \mathrm{TAU}^{+} \mathrm{Q}$
then $\mathrm{T} \vdash(\mathrm{x}) \mathrm{Px} \supset \mathrm{Qx}$

Proof: By induction on $n$ it is sufficient to prove P TAU Q implies $\mathrm{T} \vdash(\mathrm{x}) \mathrm{Px} \supset \mathrm{Qx}$

Case $n=1 \quad P$ TAU $Q$
Subcase a $P$ ALPHA $Q$ then $Q \equiv P_{1} \vee P_{2} \vee \ldots P_{n} \varepsilon I$ such that $P=P_{i}, 1<=i<=n$ In clausal form $\overline{P_{i}} v Q \varepsilon I$ or ( x$) \mathrm{Px} \supset \mathrm{Qx} \varepsilon \mathrm{I}$ Subcase b $P$ BETA $Q$ then $P \equiv Q_{1} \wedge Q_{2} \wedge \ldots Q_{n} \varepsilon I$
such that $Q=Q_{i}, 1 \ll i<=n$
In clausal form $\bar{P} v Q_{i} \varepsilon I$ or ( $x$ ) $P x \supset Q x \varepsilon I$

Case $\mathrm{n}>1 \quad \mathrm{P} \operatorname{TAU}^{\mathrm{n}} \mathrm{Q}$
Induction assumption:
$P T^{n-1} Q_{1}$ implies $T \vdash(x) P x \supset Q_{1} x$ for any $Q_{1} \varepsilon P$
Since $P T^{\prime \prime} Q$ then for some $Q_{1} \varepsilon P$,
$P \operatorname{TAU}^{n-1} Q_{1}$ and $Q_{1}$ TAU $Q$
Then $T \vdash(x) P x \supset Q_{1} x$ by induction assumption and
$T \vdash(x) Q_{1} x \supset Q x$ by case $n=1$
Therefore $T \vdash(x) P x \supset Q x \quad Q E D$

Corollary C. $1 \quad \underline{\text { Containment }}$
If $T$ is a TDB, $[P, Q] \subset P$ and $P T A U^{+} Q$
then $\|P\| \subset\|Q\|$

In terms of the graph of $I$, we are assured that if a path exists between $P$ and $Q$ in a 'vertical' direction then every INSTANCE of the TYPE $P$ is an INSTANCE of the TYPE $Q$. We can see now why acyclicity is the only practical choice for if $P T^{+} \mathrm{Q}$ and Q taU P then $\|\mathrm{P}\| \subset\|\mathrm{Q}\| \subset\|\mathrm{P}\|$ or $\|\mathrm{P}\|=\|\mathrm{Q}\|$. This would certainly be of no use in a practical TDB.

The following lemma establishes the relationship between set intersection and part 4 i in the definition of a TDB.

## Lemma C. 2 Intersection

For a TDB, T, if $P \equiv P_{1} \wedge P_{2} \wedge \ldots P_{n} \varepsilon I$

$$
\text { then } \quad\|P\|=\left\|P_{1}\right\| \cap\left\|P_{2}\right\| \cap \ldots\left\|P_{n}\right\|
$$

## Proof:

Case 1 c $\varepsilon\|\mathrm{P}\|$ (or $\mathrm{T} \vdash \mathrm{Pc}$ )
In clausal form $\overline{\mathrm{Px}} \mathrm{v}_{\mathrm{i}} \mathrm{x} \varepsilon \mathrm{I}$
for each i, $1<=i<=n$
By resolution $T \vdash P_{i} c$ implying $c \varepsilon\left\|p_{i}\right\|$ or c $\varepsilon\left\|\mathrm{P}_{1}\right\| \cap\left\|\mathrm{P}_{2}\right\| \cap \ldots\left\|\mathrm{P}_{\mathrm{n}}\right\|$

```
Case 2 \(\quad\) с \(\varepsilon\left\|P_{1}\right\| \cap\left\|P_{2}\right\| \cap \ldots\left\|P_{n}\right\|\) (or \(\mathrm{T} \mid \mathrm{P}_{\mathrm{i}} \mathrm{c}\) for each \(\mathrm{i}, 1<=\mathrm{i}<=\mathrm{n}\) ) In clausal form \(P x \vee \overline{P_{1} x} \vee \overline{P_{2} \mathrm{x}} \mathrm{v} \ldots \overline{\mathrm{P}_{\mathrm{n}} \mathrm{x}} \varepsilon \mathrm{I}\)
By resolution \(\mathrm{T} \mid \mathrm{Pc}\) implying c \(\varepsilon\|\mathrm{P}\|\)
```

Section D develops a parallel result relating the union of extensions to the formula $P \equiv P_{1} \vee P_{2} \vee \ldots P_{n}$.

Section D The Definite Component of a TDB

It has been recognized by Reiter ${ }^{[11]}$ and Minker ${ }^{[9]}$ that restricting intensional information to Horn clauses (clauses containing at most one positive literal) effectively controls the size of the proof search space without overly constraining the expressiveness of the formalism. This can be seen by viewing Horn clauses as procedures ${ }^{5]}$ in a non-deterministic programming language similar to MICRO-PLANNER ${ }^{[14]}$. Ie., the formula,

$$
\mathrm{P}_{1} \wedge \mathrm{P}_{2} \wedge \ldots \mathrm{P}_{\mathrm{n}} \supset \mathrm{P}
$$

could be programmed,

$$
\text { THE_CONSEQUENT_OF }\left(P_{1}, P_{2}, \ldots P_{n}\right) \text { IS } P ;
$$

and the clause,

$$
\overline{P_{1}} v \overline{P_{2}} v \ldots \overline{P_{n}}
$$

could be programmed,
THE_CONSEQUENT_OF $\left(P_{1}, P_{2}, \ldots P_{n}\right)$ IS INCONSISTENCY.
Proofs done in this way are reasonably efficient as only unit consequents are ever generated. Thus the maximum number of procedure firings is bounded by the number of elements in $P$.

In. this section we will consider clauses of the former form (definite clauses) to develop the desired result on union of extensions.

Definition Definite Component
Given a $T D B, T=(C, P, I, E)$, the definite component of $T, \Delta(T)$, is defined as the $\operatorname{TDB},(C, P,[W \varepsilon I \mid W$ is a definite clause], $E)$

Note that E contains only definite clauses. We can now see exactly what parts of a TDB are definite:

| W $\boldsymbol{\varepsilon}$ I | Clausal Form | Definite? |
| :---: | :---: | :---: |
| $\mathrm{P} \equiv \mathrm{P}_{1} \wedge \mathrm{P}_{2} \wedge \ldots \mathrm{P}_{\mathrm{n}}$ | $\overline{\mathrm{P}} \vee \mathrm{P}_{1}, \quad \overline{\mathrm{P}} \vee \mathrm{P}_{2}, \ldots \overline{\mathrm{P}} \vee \mathrm{P}_{\mathrm{n}}$ | yes |
|  | $\overline{P_{1}} \vee \overline{P_{2}} \vee \ldots \overline{P_{n}} \vee P$ | yes |
| $\mathrm{P} \equiv \mathrm{P}_{1} \mathrm{vP}_{2} \mathrm{v} \ldots \mathrm{P}_{\mathrm{n}}$ | $\overline{P_{1}} \vee \mathrm{P}, \overline{P_{2}} \vee \mathrm{P}, \ldots \overline{\mathrm{P}_{\mathrm{n}}} \vee \mathrm{P}$ | yes |
|  | $\overline{\mathrm{P}} \mathrm{v} \mathrm{P}_{1} \vee \mathrm{P}_{2} \vee \ldots \ldots \mathrm{P}_{\mathrm{n}}$ | no |
| $\sim(P \wedge Q)$ | $\bar{P} \mathrm{v}$ Q | no |

We would like a result parallel to lemma C. 2 but relating unions of extensions to the formula $P \equiv P_{1} \vee P_{2} \vee \ldots P_{n}$. However, as the following example shows, it would not necessarily hold:

$\|$ FEMALE $\|=$ [jane] and $\|$ WOMAN $\|=\|$ GIRL $\|=$ [ ] since $\mathrm{T} \mid \nmid$ WOMAN jane and $\mathrm{T} \nmid \mathrm{GIRL}$ jane.

So not only do we not have $\|$ Female $\|=\|$ WOMAN $\|U\|$ GIRL $\|$ but we have a TDB in which unnatural information is contained. It is hard to conceptualize jane as a "WOMAN or GIRL" without her being either a WOMAN or a GIRL. Actually,
jane is one of the two, we just can't determine which. For these reasons we insist on a TDB being "concrete".

Definition Concreteness

1) The formula $P \equiv P_{1} v P_{2} v \ldots P_{n} \varepsilon I$ is concrete iff for every $c \varepsilon C, \Delta(T) \vdash P c$ implies there is an $i$ such that $\Delta(T) \vdash P_{i} c$. 2) A TDB is concrete iff every formula of the above form is concrete.

We could have defined concreteness in terms of provability from $T$ rather than $\Delta(T)$. Unfortunately as we shall see, it turns out that at update time it would then be excessively difficult to maintain concreteness. The disadvantage in the approach taken is that equivalence must be established between $T$ and $\Delta(T)$ before the result on union of extensions can be attained. Theorem D. 1 accomplished this.

The Davis and Putnam result ${ }^{[4]}$ used in the proof of this theorem applies only for the propositional calculus. The following definition and lemma rectify this.

## Definition Propositional Component

Given a TDB, $T$, and $c \varepsilon C$ we define the propositional component of $T$ with respect to $c,{ }^{P R O P} T \mathrm{C}$ as:

$$
\operatorname{PROP}_{\mathrm{T}} \mathrm{C} \equiv[\mathrm{P} \mid \mathrm{Pc} \varepsilon \mathrm{E}] \quad \mathrm{U} \quad[\mathrm{~W} \mid \quad(\mathrm{x}) \mathrm{Wx} \varepsilon \mathrm{I}]
$$

((x)Wx represents any formula in $I$ with free variable $x$ )

Using the last example:

$$
\text { PROP }_{\mathrm{T}} \text { jane }=[\text { FEMALE }, \quad \text { FEMALE } \equiv \text { WOMAN } \vee \text { GIRL, } \sim(\text { WOMAN } \wedge \text { GIRL })]
$$

Lemma D. $1 \quad$ Propositional Equivalence
Given a consistent TDB, T, $\subset \in \mathrm{C}$ and $\mathrm{P} \varepsilon \mathrm{P}$ then $T \vdash P c$ iff $\operatorname{PROP}_{T} c \mid P$

Proof:
Part 1) Assume E U I U [ $\overline{P c}]$ is unsatisfiable. By Herbrand's theorem, if we replace each clause in $I$ with the set of clauses obtained by replacing the free variable ' $x$ ' with each member of $C$ then the remaining set is unsatisfiable. Call this the ground form of I. Since I U E was originally consistent, the ground form of I UE is. [ $\overline{\mathrm{Pc}]}$ cannot resolve against any clause which does not have c's as its ground constant. Therefore all the constants in C except $c$ are irrelevant to the inconsistency. If we construct the clause set
$[Q \mid Q c \varepsilon E] \quad U \quad[W \mid W c \varepsilon$ ground form of $I] U \quad[\bar{P}]$ then we have a propositionally unsatisfiable set. Therefore, $\operatorname{PROP}_{\mathrm{T}} \mathrm{c} \vdash \mathrm{P}$.

Part 2) Assume $\operatorname{PROP}_{\mathrm{T}} \mathrm{c} \mathrm{U}[\overline{\mathrm{P}}]$ is unsatisfiable. Clearly $\left[W c \mid W E P^{2} O P_{T} c \mathbb{U}[\bar{P}]\right]$ is unsatisfiable. This is a ground substitution of $E \mathrm{U}$ I $\mathrm{U}[\overline{\mathrm{Pc}}]$. Therefore $T$ FPc.

Theorem D. 1 also requires that one factor out certain non-definite clauses. These are the ones that allow jane to be a "WOMAN or GIRL" without the necessity of her being one of WOMAN or GIRL.

Definition Dead Clauses
Given a TDB, $T$ and $c \varepsilon C$ then the dead clauses of $T$ with respect to $c$, DEAD $_{T} c$ is defined:

$$
\operatorname{DEAD}_{\mathrm{T}} \mathrm{c} \equiv\left[\mathrm{P} \supset \mathrm{P}_{1} \mathrm{v}_{2} \vee \ldots \mathrm{P}_{\mathrm{n}} \varepsilon \operatorname{PROP}_{\mathrm{T}} \mathrm{c}\left|\operatorname{PROP}_{\Delta(\mathrm{T})} \mathrm{c}\right| \mathrm{P}, \quad \mathrm{n}>1\right]
$$

Lemma D. 2 Dropping of Dead Clauses
Given a concrete $T D B, T, c \varepsilon C$ and $W \varepsilon D E A D_{T} C$

$$
\text { then } \operatorname{PROP}_{\mathrm{T}} \mathrm{c} \sim \mathrm{DEAD}_{\mathrm{T}} \mathrm{c} \vdash \mathrm{~W}
$$

Proof:

$$
\begin{aligned}
& W=P \supset P_{1} \vee P_{2} \vee \ldots P_{n} \varepsilon \operatorname{DEAD}_{T} C \\
& \text { and } \operatorname{PROP}_{\triangle(T)} C F P \text {. } \\
& \text { By concreteness for some } i, l<=i<=n \text {, } \\
& \operatorname{PROP}_{\triangle(T)} \subset \operatorname{P}_{i} \text {. } \\
& P_{i} \text { subsumes } W \text { so } \operatorname{PROP}_{\Delta(T)} c \mid W \text {. } \\
& \text { Now } \text { DEAD }_{T} \mathrm{C} \text { contains no definite clauses so } \\
& \text { PROP }_{\Delta(T)}{ }^{c} \subset P^{P R O P} T_{T} \subset \sim D E A D_{T}^{c} \text { giving } \\
& \text { PROP }_{\mathrm{T}} \mathrm{c} \sim \operatorname{DEAD}_{\mathrm{T}} \mathrm{c} \vdash \text { W. QED }
\end{aligned}
$$

We will now prove equivalence of $T$ and $\Delta(T)$. The strategy will be to cate-
 show that if a unit Qc is provable from $T$ then $Q$ will be in that set.

Theorem D. $1 \quad T-\Delta(T)$ Equivalence
Given a consistent concrete TDB, $T, C \varepsilon C$ and $Q \varepsilon P$ then $T \vdash Q c$ iff $\Delta(T) \vdash Q c$.

Proof:
Assume $\mathrm{PROP}_{\mathrm{T}} \mathrm{C} \mid \mathrm{Q}$.
Then $\operatorname{PROP}_{\mathrm{T}} \mathrm{c} \sim \operatorname{DEAD}_{\mathrm{T}} \mathrm{c} \vdash \mathrm{Q}$ by Lemma D.2.
So $\mathrm{PROP}_{\mathrm{T}} \mathrm{C} \sim \mathrm{DEAD}_{\mathrm{T}} \mathrm{C} \mathrm{U}[\overline{\mathrm{Q}}]$ is unsatisfiable.

Define the following sets iteratively:

$$
\begin{aligned}
& \mathrm{T}_{0}=\mathrm{PROP}_{\mathrm{T}} \mathrm{C} \sim \mathrm{DEAD}_{\mathrm{T}} \mathrm{C} U[\overline{\mathrm{Q}}] \\
& \mathrm{T}_{\mathrm{i}+1}=\mathrm{T}_{\mathrm{i}} \text { when } \mathrm{Q} \varepsilon \mathrm{~T}_{\mathrm{i}} \text { or }
\end{aligned}
$$

when $T_{i}$ contains no positive units, otherwise
$=\mathrm{T}_{\mathrm{i}} \sim\left[\mathrm{X} \vee \mathrm{VPvY} \mathrm{\varepsilon} \mathrm{~T}_{\mathrm{i}}\right] \sim\left[\mathrm{X} \mathrm{V} \overline{\mathrm{P}} \mathrm{V} \mathrm{Y} \varepsilon \mathrm{T}_{\mathrm{i}}\right] \quad \mathrm{U}$
$\left[\begin{array}{ll|l}\mathrm{X} v \mathrm{Y} & \mathrm{X} v \overline{\mathrm{P}} \mathrm{v} \mathrm{Y} \varepsilon \mathrm{T}_{\mathrm{i}} \text { ] }\end{array}\right.$
where $P$ is the lexicographically first positive unit in $\mathrm{T}_{\mathrm{i}}$ and X and Y are negative predicate and positive predicate disjunctions. (possibly null)

The following is an invariant statement on $T_{i}$ :
If $W \varepsilon T_{i}$ then
A) $W=P$ such that $\operatorname{PROP}_{\Delta(T)} C \vdash P$ for some $P \varepsilon P$ or
B) $W=\bar{P}_{j}$ such that $P \equiv P_{1}$ v $P_{2}$ v $\ldots P_{n} \varepsilon I$
which is exclusive and
$\operatorname{PROP}_{\Delta(T)} C \vdash P_{i}(i \neq j)$ or
C) $W=\overline{Q_{1}} \vee \overline{Q_{2}} \vee \ldots \overline{Q_{m}} \vee P \quad(m>=1)$ such that
$P \equiv P_{1} \wedge P_{2} \wedge \ldots P_{n} \varepsilon I$ and
$\left[Q_{1}, Q_{2}, \ldots Q_{m}\right] \subset\left[P_{1}, P_{2}, \ldots P_{n}\right]$ and
$\mathrm{PROP}_{\Delta(T)} \mathrm{C} \vdash \mathrm{W}$ or
D) $W \varepsilon T_{0}$

The invariant statement is proved by the following subproof:
Subproof: By induction on i
Case $i=0 \quad$ Clear by condition $D$
Case $i>0$ If $W \varepsilon T_{i+1}$ then $W \varepsilon T_{i}$ or
$W=R(U, V)$ for $[U, V] \subset T_{i}$ with $U$ as the lexicographically first
unit in $\mathrm{T}_{\mathrm{i}}$.
${ }^{P R O P} \triangle(T) \vdash \operatorname{U}$ by $A$ and $D$ above.
$V$ is of the form $B, C$ or $D$ above:
B) $V=\overline{P_{j}}$ such that $P \equiv P_{1} \vee P_{2} v \ldots P_{n} \varepsilon I$ which is exclusive and $\operatorname{PROP}_{\Delta(T)}{ }^{c} \vdash{ }^{-} P_{i} \quad(i \neq j)$
$U=P_{j}$ and $\operatorname{PROP}_{\Delta(T)} \vdash P_{j}$.
But $\overline{P_{i}} \vee \overline{P_{j}} \varepsilon I$ by exclusiveness.
This violates the consistency of $T$, so $V \neq \bar{P}_{j}$.
C) $v=\overline{Q_{1}} \vee \overline{Q_{2}} \vee \ldots \overline{Q_{m}} \vee P \quad(m>=1)$
$P \equiv P_{1} \wedge P_{2} \wedge \ldots P_{n} \varepsilon I$ and
$\left[Q_{1}, Q_{2}, \ldots Q_{m}\right] \subset\left[P_{1}, P_{2}, \ldots P_{n}\right]$ and $\mathrm{PROP}_{\Delta(\mathrm{T})} \mathrm{c}$ - V .
$\mathrm{U}=\mathrm{Q}_{\mathrm{i}}$ for some $\mathrm{i}, 1<=\mathrm{i}<\mathrm{m}$.
Clearly $W$ has the same form as $C$ with $\operatorname{PROP}_{\Delta(T)} \vdash^{W}$
unless $m=1$ in which case $W=P$ with $\operatorname{PROP}_{\Delta(T)} \mid P$
which is in the form $A$.
D) $V \varepsilon \operatorname{PROP}_{T} \mathrm{c} \sim \operatorname{DEAD}_{\mathrm{T}} \mathrm{c}$ U [ $\left.\overline{\mathrm{Q}}\right]$

Case $1 \quad V=\overline{P_{1}}$ v $P_{2} \varepsilon I$, trivially $\operatorname{PROP}_{\Delta(T)}{ }^{c} \vdash \mathrm{~V}$.
$U=P_{1}$ so $\operatorname{PROP}_{\triangle(T)} \vdash P_{2}$ which is of form $A$.
$\underline{\text { Case } 2} \mathrm{~V}=\overline{P_{1}} \vee \overline{P_{2}} \vee \ldots \overline{P_{n}} \vee P \varepsilon I$
See C above.
Case $3 \quad V=\overline{P_{i}} \vee \overline{P_{j}} \quad(i<j)$ where $P \equiv P_{1} \vee P_{2} \vee \ldots P_{n} \varepsilon I$ which is exclusive.

Assume without loss of generality that $U=P_{i}$.
Then $W=\bar{P}_{j}$ which is in the form $B$.
Case $4 \quad V=\bar{P} \vee P_{1} \vee P_{2} \vee \ldots P_{n}, U=P$.
Since ${ }^{P R O P}{ }_{\triangle(T)} C \vdash P$ then $V \varepsilon \operatorname{DEAD}_{T} C$.
But then $\mathrm{V} \notin \mathrm{T}_{0}$ which is a contradiction.
Case $5 \quad \mathrm{~V}=\overline{\mathrm{Q}}$
But then $U=Q$ was the lexicographically first unit in $T_{i}$ so by construction $T_{i+1}=T_{i}$.

This completes the subproof of the invariant statement on $T_{i}$.

As a corollary, $\mathrm{T}_{\mathrm{i}}$ contains no non-unit positive clauses.

By the results of Davis and Putnam ${ }^{[4]}, \mathrm{T}_{\mathrm{i}+1}$ is unsatisfiable whenever $\mathrm{T}_{\mathrm{i}}$ is. Since $\mathrm{T}_{0}$ is unsatisfiable, by induction for all $\mathrm{i}, \mathrm{T}_{\mathrm{i}}$ is unsatisfiable.

Also, $T_{i}$ contains a positive unit for every $i$, for if not then the interpretation in which every predicate is taken as false is a model for $\mathrm{T}_{\mathrm{i}}$.

Note that $T_{i+1}$ has at least one less predicate symbol than $T_{i}$ (the lexicongraphically first unit in $T_{i}$ ) unless $T_{i+1}=T_{i}$. Since $T_{i}$ always contains a positive unit and since $P$ is finite, then $T_{i+1}=T_{i}$ for some $i$. At this point $Q \in T_{i}$ since $T_{i}$ contains a positive unit. By the invariant statement on $\mathrm{T}_{\mathrm{i}}$,

$$
\mathrm{PROP}_{\Delta(\mathrm{T})^{\mathrm{c}}}{ }^{\circ} \mathrm{Q} \text { QED. }
$$

We can now relate part 4 ii in the definition of a TDB to the union of externsion. .

Lemma D. 3 Union
Given a consistent concrete TDB, $T$ and a formula

$$
P \equiv P_{1} \vee P_{2} \vee \ldots P_{n} \varepsilon I
$$

then $\|P\|=\left\|P_{1}\right\| U\left\|P_{2}\right\| \quad U \ldots\left\|P_{n}\right\|$. Proof:

Part 1 c $\varepsilon\|\mathrm{P}\|$ or $\mathrm{T} \mid \mathrm{Pc}$.
By theorem D.1, $\Delta(T) \vdash P c$.
By concreteness, for some $i, \Delta(T) \vdash P_{i} c$
giving $T \vdash P_{i} c$ or $c \varepsilon\left\|P_{i}\right\|$.
Part 2) $c \in\left\|P_{i}\right\|$ or $T \vdash P_{i} c$ for some $i$.
In clausal form $\overline{P_{i}}$ v $P \varepsilon I$.
By resolution $T \vdash P c$ or $c \varepsilon\|P\|$.

Until now we have not differentiated between disjoint and non-disjoint union of extensions of the form $P \equiv P_{1} \vee P_{2} v \ldots P_{n} \varepsilon I$. However, in most (but not all) applications we would like disjointness strictly enforced.

Lemma D. 4 Disjointness
Given a consistent $T D B, T$, and an exclusive formula $P \equiv P_{1} \vee P_{2} \vee \ldots P_{n} \varepsilon I$
then for each $i, j, \quad 1 \ll i<j<n, \quad\left\|p_{i}\right\| \cap\left\|P_{j}\right\|=[1$.
Proof: Let $c \varepsilon\left\|P_{i}\right\| \cap\left\|P_{j}\right\|$.
Then $T \vdash P_{i} c$ and $T \nmid P_{j} c$.
But $\overline{P_{i}} v \overline{P_{j}} \varepsilon I$.
This violates consistency, so no such $c$ exists.

Corollary D. 1 Disjoint Union
Given a consistent concrete TDB, $T$, and an exclusive formula

$$
\begin{aligned}
& P \equiv P_{1} \vee P_{2} \vee \ldots P_{n} \varepsilon I \\
& \text { then }\|P\|=\left\|P_{1}\right\| \oplus\left\|P_{2}\right\| \oplus \ldots\left\|P_{n}\right\| \cdot
\end{aligned}
$$

In summary:

1) For conjunctions $\|P\|=\left\|P_{1}\right\| \cap\left\|P_{2}\right\| \cap \ldots\left\|P_{n}\right\|$

Furthermore if $T$ is consistent and concrete:
2) For disjunctions $\|P\|=\left\|P_{1}\right\| U\left\|P_{2}\right\| U \ldots P_{n} \|$
3) For exclusive disjunctions $\|P\|=\left\|P_{1}\right\| \oplus\left\|P_{2}\right\| \oplus \ldots\left\|P_{n}\right\|$

## Section E Transformation of a TDB to its Reduced Form

One use of a TDB is to answer the question "Is TトPc". Reiter for one requires this for his "typed unification algorithm" as described in [10,11]. Algorithm E. 1 below computes [ $\mathrm{P}|\mathrm{T}| \mathrm{Pc}$ ] given $\mathrm{c} \varepsilon \mathrm{c}$, for a concrete TDB , and detects any inconsistency in $\mathrm{PROP}_{\mathrm{T}} \mathrm{c}$.

As $[P|T| P c]$ may contain a large number of $P$ for any given $c$, we define a reduced form of $T, R(T)$, which contains only the Pc's necessary to span $E$. This corresponds to associating INSTANCES with primitive semantic categories in $[7,8,9]$. Thus, we can determine if $c \varepsilon\|P\|$ by looking at the primitive categories below P.

We have shown that formulae of the form $\overline{\mathrm{P}} \vee \mathrm{P}_{1} \vee \mathrm{P}_{2} \vee \ldots \mathrm{P}_{\mathrm{n}} \varepsilon \mathrm{I}$ can be removed with no effect when $T$ is both concrete and consistent. This motivates computing on the Horn component of concrete TDBs.

## Definition Horn Component

Given a TDB, $T=(C, P, I, E)$, define the Horn component of $T, H(T)$, as

$$
H(T)=(C, P,[W \varepsilon I \mid W \text { is a Horn clause }], E)
$$

Note that E contains only Horn clauses. Looking at this case by case:

| W E I | Clausal Form | Definite? | Horn? |
| :---: | :---: | :---: | :---: |
| $\mathrm{P} \equiv \mathrm{P}_{1} \wedge \mathrm{P}_{2} \wedge \ldots \mathrm{P}_{\mathrm{n}}$ | $\overline{\mathrm{P}} \mathrm{VP}_{1}, \quad \overline{\mathrm{P}} \mathrm{vP}_{2}, \ldots \bar{P} \mathrm{P} \mathrm{P}_{\mathrm{n}}$ | yes | yes |
|  | $\overline{P_{1}} \vee \overline{P_{2}} \vee \ldots \overline{P_{n}} \vee \mathrm{P}$ | yes | yes |
| $\mathrm{P} \equiv \mathrm{P}_{1} \mathrm{v} \mathrm{P}_{2} \mathrm{v} \ldots \mathrm{P}_{\mathrm{n}}$ | $\overline{P_{1}} \vee P, \overline{P_{2}} \vee P, \ldots \overline{P_{n}} \vee P$ | yes | yes |
|  | $\bar{P} \vee P_{1} \vee P_{2} \vee \ldots P_{n}$ | no | no |
| $\sim(\mathrm{P} \wedge \mathrm{Q})$ | $\bar{P}$ v $\bar{Q}$ | no | yes |

The following algorithm computes $[P|T| P c]$ given $c \varepsilon C$

Algorithm E. $1 \quad$ For computing DOMAIN $_{T}$ c given $\mathrm{c} \varepsilon \mathrm{C}$

$$
\begin{aligned}
& \mathrm{T}_{0}<-\mathrm{PROP}_{\mathrm{H}(\mathrm{~T})} \mathrm{c} \\
& \mathrm{~S}_{0}<-[1 \\
& \text { FOR } \mathrm{i}=0 \text { to infinity DO }
\end{aligned}
$$

## BEGIN

IF $\mathrm{T}_{\mathrm{i}}$ contains no positive unit
THEN DOMAIN $\mathrm{T}^{\mathrm{c}} \equiv \mathrm{s}_{\mathrm{i}}$,
$\mathrm{k}<--\mathrm{i}$, EXIT
$\mathrm{P}<--$ the lexicographically first positive unit in $T_{i}$ $\mathrm{IF} \overline{\mathrm{P}} \varepsilon \mathrm{T}_{\mathrm{i}}$

THEN PROP $_{T} c$ is inconsistent,
DOMAIN ${ }_{T}{ }^{c}$ is undefined, EXIT
$S_{i+1}<--S_{i} U[P]$

$U\left[X \vee Y \mid X \vee \bar{P} v Y \varepsilon T_{i}\right]$
where $X$ and $Y$ are disjunctions of negative and positive predicates respectively (possibly null).

END

Example: Using the I of diagram C.l and letting:

$$
E=[S I N G L E \text { john, MALE john] }
$$

and $\mathrm{c}=$ john, the algorithm will produce the following values:

| i | P | $\mathrm{T}_{\mathrm{i}} \sim \mathrm{T}_{i+1} \quad($ dropped） | $\mathrm{T}_{\mathrm{i}+1} \sim \mathrm{~T}_{\mathrm{i}}$（added） |
| :---: | :---: | :---: | :---: |
| 0 | MALE | MALE |  |
|  |  | MAN $\supset$ MALE |  |
|  |  | BOY $\triangle$ MALE |  |
|  |  | MALE $\supset$ PERSON | PERSON |
|  |  | $\sim$（MALE $\wedge$ FEMALE） | FEMALE |
|  |  | MALE $\wedge$ ADULT $\supset$ MAN | ADULT $ゝ$ MAN |
|  |  | MALE へ CHILD $\boldsymbol{\sim}$ BOY | CHILD $\frown \mathrm{BOY}$ |
| 1 | PERSON | PERSON |  |
|  |  | FEMALE $\supset$ PERSON |  |
|  |  | ADULT $\triangle$ PERSON |  |
|  |  | CHILD $~ P ~ P E R S O N$ |  |
| 2 | SINGLE | SINGLE |  |
|  |  | BACHELOR SINGLE |  |
|  |  | MAIDEN SINGLE |  |
|  |  | SINGLE $\supset \mathrm{ADULT}$ | ADULT |
|  |  | $\sim$（SINGLE＾MARRIED） | $\overline{\text { MARRIED }}$ |
|  |  | MAN＾SINGLE $\longrightarrow$ BACHELOR | MAN $\supset \mathrm{BACHELOR}$ |
|  |  | SINGLE＾WOMAN $\supset$ MAIDEN | WOMAN $\triangle$ MAIDEN |
| 3 | ADULT | ADULT |  |
|  |  | MAN $\supset$ ADULT |  |
|  |  | WOMAN $\supset$ ADULT |  |
|  |  | MARRIED $\supset$ ADULT |  |
|  |  | $\sim$（ADULT $\wedge$ CHILD $)$ | $\overline{\text { CHILD }}$ |
|  |  | ADULT $\supset$ MAN | MAN |
|  |  | FEMALE へ ADULT $\longrightarrow$ WOMAN | FEMALE $\supset$ WOMAN |
| 4 | MAN | MAN |  |
|  |  | BACHELOR $\supset$ MAN |  |
|  |  | MAN $工$ BACHELOR | BACHELOR |
| 5 | BACHELOR | BACHELOR |  |

$\mathrm{T}_{6}$ contains no positive unit. Thus:
DOMAIN $_{\mathrm{T}} \mathrm{john}=$ [MALE, PERSON, SINGLE, ADULT, MAN, BACHELOR]

The algorithm can be implemented by hash indexing predicate symbols into a copy of the formulae in I in which they appear (only one copy is made for each formula). For efficiency, positive units are kept in a separate list. When a formula of the form $\mathrm{X} v \mathrm{P} \mathrm{v} \mathrm{Y} \in \mathrm{I}$ is to be dropped it is tagged as deleted. When a formula of the form $X \vee \bar{P} v Y$ is to be replaced by $X V Y$ the predicate symbol $\overline{\mathrm{P}}$ is deleted from the copy. If a positive unit results it is added to the positive unit list. If the null clause results, DOMAIN ${ }_{T}{ }^{c}$ is declared to be undefined and the original clause $\bar{P} v \bar{Q}$ that caused the contradiction can be printed for inspection.

If we assume that the time taken to delete the symbol $\overline{\mathrm{P}}$ from $\mathrm{X} v \overline{\mathrm{P}} \mathrm{v} \mathrm{Y}$ is constant, the time taken to add a symbol to the positive unit list is constant and the hash indexing is performed in constant time (by design) then the following is a bound on the time complexity ${ }^{[1]}$ of the algorithm:

$$
\circlearrowleft\left(\sum_{W \in \operatorname{PROP}_{H(T)^{c}}} \not \text { predicate symbols in } W \quad\right.
$$

Theorem E. 1

## Algorithm E. 1 Correctness

Given a concrete TDB, $T$, and $c \varepsilon C$
If $\mathrm{PROP}_{\mathrm{T}} \mathrm{C}$ is consistent
then $\quad \operatorname{DOMAIN}_{\mathrm{T}} \mathrm{C}=[\mathrm{P}|\mathrm{T}| \mathrm{Pc}]$
otherwise DOMAIN ${ }_{T}$ c is undefined
Proof:
First, note that the class of Horn clauses is closed under resolution
(ie. $R\left(W_{1}, W_{2}\right)$ is Horn whenever $W_{1}$ and $W_{2}$ are). It follows that the only positive clauses in $\mathrm{T}_{\mathrm{i}}$ for all i are units. This is needed to apply the Davis and Putnam ${ }^{[4]}$ theorem below.

Case A PROP $_{T} \mathrm{C}$ is consistent
Subcase $1 \quad P \varepsilon$ DOMAIN $_{T}$ c.
For some $i, P \varepsilon T_{i}$ giving $\operatorname{PROP}_{H(T)} c \vdash P$
and hence $\mathrm{PROP}_{\mathrm{T}} \mathrm{C} \vdash \mathrm{P}$
Subcase $2 \mathrm{~T} \vdash \mathrm{Pc}$
Assume $\mathrm{P} \notin \mathrm{T}_{\mathrm{i}}$ for all i
Define $H^{\prime}(T)=H(T) U[\bar{P}]$
Starting the algorithm with $H^{\prime}(T)$ rather than $H(T)$ we produce
$T_{i}^{\prime}$ rather than $T_{i}$.
Note that when defined,

$$
T_{i}^{\prime}=T_{i} U[\bar{P}]
$$

The algorithm will terminate in one of two ways:

1) $[P, \bar{P}] \subset T_{i}^{\prime}$ for some $i$ $\left([Q, \bar{Q}] \not \subset T_{i}^{\prime}\right.$ when $Q \varepsilon P$ and $Q \neq P$
since $T_{0}$ is consistent)
But then $P \varepsilon T_{i}^{\prime}$ contradiction
2) $T_{k}^{\prime}$ contains no positive unit; but then the interpretation in which every predicate symbol is false is a model for $T_{k}^{\prime}$. Since $T \vdash P c$ by theorem $D .1, \Delta(T) \vdash P c$ giving $\mathrm{H}(\mathrm{T}) \vdash \mathrm{Pc}$ or $\mathrm{T}_{0} \mathrm{U}[\overline{\mathrm{P}}]=\mathrm{T}_{0}^{\prime}$ is unsatisfiable. By Davis and Putnam ${ }^{[4]}, \mathrm{T}_{\mathrm{k}}^{\prime}$ is unsatisfiable which is a contradiction. Therefore $\mathrm{P} \varepsilon \mathrm{T}_{\mathrm{i}}$ for some i .
The algorithm must terminate since $\mathrm{T}_{\mathrm{i}+1}$ contains at least one fewer predicate symbol then $\mathrm{T}_{\mathrm{i}}$.
Case B ${ }^{\text {RROP }_{T} c}$ is unsatisfiable
Statement: $\operatorname{PROP}_{H(\dot{T})} \mathrm{c}$ is unsatisfiable
Subproof: By lemma D. 2 PROP $_{T} \mathrm{c} \sim \operatorname{DEAD}_{T} \mathrm{c}$ is unsatisfiable. If
we define $T_{0}$ as $\operatorname{PROP}_{T}{ }^{c} \sim D E A D_{T}$ c and let the algorithm define $T_{i}$ for each i, then the invariant statements of theorem D .1 hold with one addition: $W \mathcal{E} \mathrm{~T}_{\mathrm{i}}$ may be the null clause.

The algorithm will terminate in one of two ways:

1) $[P, \bar{P}] \subset T_{i}$ for some $i$ where $P$ is the lexicographically first unit in $T_{i}$. By statements $A$ and $B$ of theorem $D .1$, ${ }^{P_{R O P}} \Delta(T)^{C} \vdash P$ and
for some $Q \varepsilon P, \quad \bar{P} \vee \bar{Q} \varepsilon I$ and $P R O P_{\triangle(T)} \subset \vdash Q$. Since $\overline{\mathrm{P}} \mathrm{V} \overline{\mathrm{Q}} \varepsilon H(\mathrm{~T})$ and $\triangle(\mathrm{T}) \subset \mathrm{H}(\mathrm{T}), \mathrm{PROP}_{H(T)}{ }^{\mathrm{C}}$ is inconsistent.
2) By the results of Davis and Putnam ${ }^{[4]}$, for each $i, T_{i}$ is unsatisfiable. Since $T_{i+1}$ contains at least one less literal than $T_{i}$, for some $k, T_{k}$ contains no positive literals. The interpretation in which every predicate symbol is false is a model for $T_{k}$ unless $T_{k}$ contains the null clause. Since $T_{k}$ is unsatisfiable it must contain the null clause. $\mathrm{T}_{0}$ doesn't contain the null clause so for some $i$, $[P, \bar{P}] \subset T_{i}$ where $P$ is the lexicographically first unit $T_{i}$. In this case though, the algorithm will have terminated as in case A.

This ends the subproof.

As in the subproof, the algorithm will not terminate with $\mathrm{T}_{\mathrm{k}}$ containing no units (Starting with $\mathrm{T}_{0}=\mathrm{PROP}_{\mathrm{H}(\mathrm{T})} \mathrm{c}$ unsatisfiable). Therefore, $[P, \bar{P}] \subset T_{i}$ for some i. The algorithm will stop with DOMAIN $_{\mathrm{T}} \mathrm{c}$ undefined. QED

This ends the correctness proof of algorithm E.l

The following corollary is used in the proof of the update algorithm.

## Corollary E. $\quad \triangle(T)$ - DOMAIN $T$ Equivalence

Given a TDB, $T$ (not necessarily concrete or consistent) and ce $\mathcal{C}$

1) If $P \in$ DOMAIN $_{T} C$ then $\Delta(T) \vdash \operatorname{Pc}$
2) If $\Delta(T) \vdash \operatorname{Pc}$ then $P \varepsilon \operatorname{DOMAIN}_{T} C$ or $\operatorname{DOMAIN}_{T} c$ is undefined Proof:

Part $1 \quad P \varepsilon$ DOMAIN $_{T}$ c
The invariant statements of theorem D. 1 hold with the addition
that $W$ may be the null clause.
Therefore $\Delta(T) \vdash P c$
Part $2 \Delta(T) \vdash P c$
Hence $H(T) \vdash P c$.
If T is consistent then by theorem E.1, Case A, subcase 2, $P \varepsilon T_{i}$ for some $i$ (we do not need theorem D.l here) or P $\varepsilon$ DOMAIN $_{\mathrm{T}} \mathrm{C}$.

If T is unsatisfiable then by theorem E.l, Case $B, H(T)$ is unsatisfiable and $\operatorname{DOMAIN}_{T} \mathrm{c}$ is undefined. QED

As a TDB, $T$, becomes large, [DOMAIN $T^{C} \mid c \in C$ ] may become very large. The following allows us to save only the Pc that span E. Ie., store only the 'lowest' extensions in the graph.

Definition The Reduced or Canonical TDB
Given a consistent concrete TDB,

$$
\begin{aligned}
& \mathrm{T}=(\mathrm{C}, \mathrm{P}, \mathrm{I}, \mathrm{E}) \text {, the reduced } \mathrm{TDB}, \mathrm{R}(\mathrm{~T}) \text {, is defined: } \\
& R(T)=\left(C, P, I,\left[P C \mid P \varepsilon \operatorname{DOMAIN}_{T} C\right. \text { and }\right. \\
& \text { if } \left.Q \varepsilon \operatorname{DOMAIN}_{\mathrm{T}} \mathrm{C} \text { then not } \mathrm{Q} \mathrm{TAU}^{+} \mathrm{P}\right] \text { ) }
\end{aligned}
$$

Using the example of diagram C.l:

| $[\mathrm{P} \mid \mathrm{Pc} \varepsilon \mathrm{E}]$ | $=$ |
| ---: | :--- |
| DOMAIN $_{\mathrm{T}} \mathrm{C}$ | [SINGLE, MALE] |
|  | [MALE, PERSON, SINGLE, |
|  |  |
|  | ADULT, MAN, BACHELOR] |

but $\left[\mathrm{P} \mid \mathrm{Pc} \varepsilon \mathrm{R}(\mathrm{T})^{\prime} \mathrm{s}\right.$ extension] $=$ [BACHELOR]
This is a good space reduction. In fact, in no case is $R(T)$ 's extension larger than $T^{\prime} s$. Note that we cannot assume that the concreteness or consistency of $R(T)$ follows from that of $T$.

Lemma E. $1 \quad \underline{\text { Spanning }}$
Given a consistent concrete TDB, T,
if $P \varepsilon$ DOMAIN $_{T} C$ then for some $Q \in P$ with $Q \subset \mathcal{R}(T)$ 's extension, Q TAU* $P$

Proof: Assume for each $n>=0$ with $Q \subset \varepsilon R(T)$ 's extension, that not $Q$ TAUn $P$

By definition of $R(T)$ 's extension, $P c \varepsilon R(T)$ 's extension Choosing $n=0, Q=P$ we have a contradiction for $Q \operatorname{TAU}^{0} P$. $R(T)$ 's extension is said to span [Pc|T| $\mid$ Pc].

Getting back to the original problem, "Is $T \nmid P c$ ?" we see that we need only scan $R(T)$ 's extension for $Q c$ such that $Q T A U^{*} P$.

Theorem E. $2 \quad T-R(T)$ Equivalence
Given a consistent concrete TDB, T, then if $P c \varepsilon R(T)$ 's extension then $T \vdash P c$
and if $\operatorname{Pc} \varepsilon E$ then $R(T) \vdash P c$
Proof:
Part 1) Assume Pc $\varepsilon R(T)$ 's extension. P $\varepsilon \operatorname{DOMAIN}_{\mathrm{T}}{ }^{c}$ so by theorem E.l, $\mathrm{T} \mid \mathrm{Pc}$

Part 2) Assume Pc $\varepsilon$ E
or $P \varepsilon D^{\prime} M_{T} C$.
By the spanning lemma (E. 1 ) for some $Q \varepsilon P$, such that $Q \subset \in R(T)$ 's extension, $Q T A U^{*} P$.
By the generalization lemma (C.l), R(T) -Pc QED

## Corollary E. 2

Given a consistent concrete TDB, T, $\subset \varepsilon C, P \varepsilon P$,

$$
T \vdash P c \text { iff } R(T) \vdash P c
$$

Corollary E. 3 Concreteness of $R(T)$
Given a consistent concrete $T D B, T, R(T)$ is concrete
Proof:
Let $P \equiv P_{1} \quad v P_{2} v \ldots P_{n} \varepsilon I$
Assume for some c $\varepsilon C, \Delta(R(T)) \vdash P c$
Then $T \nmid P c$ by theorem E. 2
and $\Delta(T) \vdash P c$ by theorem $D .1$
and $\Delta(T) \vdash P_{i} c$ by $T$ 's concreteness (for some $i, \quad l \ll i<n$ )
This gives $\mathrm{P}_{\mathrm{i}} \mathrm{c} \mathcal{E}$ DOMAIN $\mathrm{T}^{\mathrm{c}}$ by theorem D. 1
By the spanning lemma (E.1), for some $Q \subset \varepsilon R(T)$ 's extension, $Q T A U^{*} P_{i}$
By the generalization lemma (C.1) (which resolves only definite clauses $), \Delta(R(T)) \vdash P_{i} c \quad Q E D$

Corollary E. 4 Consistency of $R(T)$
Given a consistent concrete $T D B, T, R(T)$ is consistent
Proof:
Let $S=\left[P C \mid P \varepsilon \operatorname{DOMAIN}_{\mathrm{T}} \mathrm{c}\right] \mathrm{U}$

$$
\left[\overline{\mathrm{Pc}} \mid \mathrm{P} \in \mathrm{P} \quad \text { and } \mathrm{P} \notin \mathrm{DOMAIN}_{\mathrm{T}} \mathrm{c}\right]
$$

$S$ is a model for $H(T)^{[12]}$.

```
If it is not a model for \(T\) then for some
    \(\mathrm{P} \equiv \mathrm{P}_{1} \vee \mathrm{P}_{2} \mathrm{v} \ldots \mathrm{P}_{\mathrm{n}} \varepsilon \mathrm{I}\),
\(\mathrm{P} \varepsilon \operatorname{DOMAIN}_{\mathrm{T}} \mathrm{c}\) and each \(\mathrm{P}_{\mathrm{i}}\) \& DOMAIN \(\mathrm{T}, \quad 1 \ll \mathrm{i}<=\mathrm{n}\)
This contradicts concreteness, so S is a model for T .
\(R(T)\) is concrete so similarly \(S\) is a model for \(R(T)\). QED
```

Thus $R(T)$ is a suitable replacement for a consistent TDB, T.

Section F Updating a TDB

Thus far we have shown that a TDB will have the desired set theoretic properties if concreteness and consistency are maintained. We have given a canonical (reduced) form of the TDB that can be efficiently computed while conserving both space and time in answering "Is $T \vdash P c$ ?". We must now specify an algorithm that will update the canonical TDB while guaranteeing concreteness and consistency.

Given a concrete and consistent TDB, $T$, and $\subset \in \mathcal{C}$ the algorithm accepts additions to and deletions from DOMAIN $_{T} c$ so as to leave the resulting TDB concrete and consistent. It is assumed that originally $T=R(T)$. The algorithm will produce $\mathrm{T}^{\prime}=\mathrm{R}\left(\mathrm{T}^{\prime}\right)$.

Algorithm F.1 For updating a canonical TDB T, given c $\mathcal{E} \mathrm{C}$
UPDATE $_{\mathrm{T}} \mathrm{c}$ :
BEGIN
WRITE ( $c$, "has the root properties:", [P|Pc EE])
S: INPUT (A $\subset P$ (additions) and $D \subset P$ (deletions) )
IF $\quad[\mathrm{Pc} \mid \mathrm{P} \varepsilon \mathrm{D}] \not \subset \mathrm{E}$ THEN
WRITE ( $D \sim[P \mid \operatorname{Pc} \varepsilon E]$, "cannot be deleted, try again") GOTO S
$\mathrm{L}: \mathrm{T}^{\prime}<-(\mathrm{C}, \mathrm{P}, \mathrm{I}, \mathrm{E} \mathrm{U}[\mathrm{Pc} \mid \mathrm{P} \boldsymbol{\varepsilon} \mathrm{A}] \sim[\mathrm{Pc} \mid \mathrm{P} \boldsymbol{\varepsilon} \mathrm{D}])$
Calculate DOMAIN $_{T}{ }^{\prime} \mathrm{C}$
CONCRETE <-- TRUE
E: IF DOMAIN ${ }_{T}$ ' $C$ is undefined (because $\bar{P} \vee \bar{Q} \varepsilon I$ ) THEN WRITE (c, "cannot be both a", P, "and a", Q, "try again") GOTO S

```
C: FOR EACH P \equiv P P v v P % v ... P P | | I such that
    P \varepsilon DOMAIN T'C but no P Pi
        WRITE ("A", P, "must also be one of", P}\mp@subsup{P}{1}{},\mp@subsup{P}{2}{},\ldots.. P P , 
        "add one of them")
        CONCRETE <-- FALSE
IF NOT CONCRETE THEN
    INPUT (A'\subset P (additions) )
    A <-- A U A'
    GOTO L
Calculate R(T') given DOMAIN T'C and T' *
T'<-- R(T').
WRITE ("update accepted")
END
```

Note that in the step marked *, DOMAIN $T^{\prime} c_{1}$ for $c_{1} \neq c$ need not be recalculated as $\operatorname{DOMAIN}_{\mathrm{T}}{ }^{\prime} \mathrm{c}_{1}=\operatorname{DOMAIN}_{\mathrm{T}}{ }_{1}$. The following theorem gives the update properties desired.

## Theorem F. 1 Algorithm F. 1 Correctness

Given a consistent concrete and canonical TDB, T and c $\varepsilon$ C then the resultant canonical $T D B, T^{\prime}$, is consistent and concrete.

Proof:

## Part 1 Concreteness

Let $P \equiv P_{1} \vee P_{2} \vee \ldots P_{n} \in I$ and $\Delta\left(T^{\prime}\right) \vdash P c$ By corollary E.1, since DOMAIN $T^{\prime}$ ' $C$ is defined in order for algorithm termination, $\mathrm{P} \varepsilon \operatorname{DOMAIN}_{\mathrm{T}} \mathrm{C}$. Since the algorithm terminated (CONCRETE is TRUE), for some $i, P_{i} \varepsilon$ DOMAIN $_{T}{ }^{\prime}$ C. Corollary E. 1 gives $\Delta\left(T^{\prime}\right) \vdash P_{i} c$.

## Part 2 Consistency

If $T^{\prime}$ is not consistent then since $T$ is consistent, PROP $_{T}{ }^{\prime} \mathrm{C}$ must be unsatisfiable. Theorem E. 1 applies since $\mathrm{T}^{\prime}$ is concrete saying DOMAIN $\mathrm{T}^{\prime} \mathrm{C}$ is undefined. This contradicts termination of the algorithm. Therefore $\mathrm{T}^{\prime}$ is consistent.

By corollaries E. 3 and E.4, $R\left(T^{\prime}\right)$ is concrete and consistent. QED

The following is a sample update using the $I$ of diagram C. 1 and an empty $E$.

| Input | Response | E or E' |
| :---: | :---: | :---: |
| - Update john | - john has the root properties [ ] | $\mathrm{E}=$ [ ] |
| - $\mathrm{A}=[$ ADULT $]$ | - An ADULT must be one of MARRIED or SINGLE, add one. | $\mathrm{E}^{\prime}=$ [ADULT john] |
| - $\mathrm{A}=[\mathrm{MALE}, \mathrm{SINGLE}$ ] | - Update accepted | $\begin{aligned} E^{\prime}= & {[\text { ADULT john, MALE john },} \\ & \text { SINGLE john }] \end{aligned}$ |
|  |  | $E^{\prime}=$ [BACHELOR john] |
| - Update john | - john has the root properties [BACHELOR] | $\mathrm{E}=$ [BACHELORjohn] |
| - $\mathrm{A}=[\mathrm{MARRIED}]$ and | - [SINGLE] cannot be |  |
| $\mathrm{D}=$ [SINGLE ] | deleted, try again |  |
| - $\mathrm{A}=$ [MARRIED] | - john cannot be both | $E^{\prime}=[$ MARRIED john, |
|  | MARRIED and SINGLE, try again | BACHELORjohn] |
| $\begin{aligned} -\mathrm{A} & =[\text { MARRIED }] \text { and } \\ \mathrm{D} & =[\text { BACHELOR }] \end{aligned}$ | - An ADULT must be one of MALE or FEMALE, add one | $E^{\prime}=[$ MARRIED john] |
| - $\mathrm{A}=$ [MALE] | - Update accepted | $E^{\prime}=$ [MARRIEDjohn, MALE john] |

It may seem redundant that we must "Add MALE" when we did not explicitly delete MALE. However, when BACHELOR is deleted, the algorithm has no way in general of determining if MAN and/or SINGLE are to remain in the TDB. Rather than trying to second guess the user, the algorithm asks him to correct any dropped information.

Before the first update, when $E=[$, for the update theorem to apply, $T$ must be concrete and consistent. It is certainly concrete. In order for it to be consistent, I must be consistent. The interpretation in which all predicate symbols are false under the interpretation is a model for $I$, so it is consistent. Thus by induction on the update theorem we are assured that if we start with $\mathrm{E}=$ [ ] then T will always be concrete and consistent after the update.

Although there are no inconsistencies in $I$, there may be constraints that prevent certain kinds of updates from taking place. By this we mean that given some $P \varepsilon P$, for no $c \varepsilon C$ is $P c \varepsilon E$ while $T$ is consistent. Ie. $\|P\|=[$ ] always.

For example, consider the following:
$\mathrm{I}=$


Clearly, I ト (x) $\overline{\mathrm{P}_{1}} \mathrm{x}$.

Therefore if the $T D B$ is to be kept consistent, $\left\|P_{1}\right\|=$ [ ] always. This is clearly a case of bad structuring of $I$. It can be avoided by ensuring that
for all $P \in P, I U[P x]$ is consistent. This can be guaranteed by letting $E=[P c]$ for any $c \in C$ and calculating $D^{\prime} O M A I N T C$. If undefined, then $I$ is badly structured above $P$.

Summary and Conclusions


#### Abstract

A generalized structure has been proposed for Reiter's typed database [10] to replace the more restricted notion of the ISA hierarchy. It provides a rich structuring facility and imposes only the natural requirements of so-called concreteness and consistency. Results have been given to ensure that the database has the desired set theoretic properties. An update algorithm has been specified that guarantees concreteness and consistency along with a technique for testing if a specific element is a member of a given domain. A means for testing a non-atomic formula against the database was not included and is an open topic.


While traditional relational databases suggest no need for a typed database, work in artificial intelligence and inferential database systems often are deficient because of the need for a more interdependant domain structure. Since the TDB provides the most rudimentary level of inferencing it must be well structured and mathematically complete in order that inferencing mechanisms built on it stand on firm ground. It must not limit the descriptive power of a host inferential database system, thereby reducing its applicability. We suggest that the proposed structure and algorithms for a typed database are adequate for managing the domain structure of inferential database systems.

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Appendix A Dictionary of Symbols

## Sets:

[ ] - Used in set definitions as a replacement for $\}$
$\varepsilon, \mathcal{E} \quad$ Set membership and non-membership
$\subset, \not \subset-$ Set inclusion and non-inclusion
$\cap$, $U$ - Set intersection and union
$\oplus \quad-\quad$ Disjoint union
$\sim \quad-\quad$ Set difference
| - Set qualification (read "such that")
$\|\mathrm{P}\| \quad-\quad$ Extension of a predicate, (see section C )

Predicate Calculus Formulae:

$$
\begin{array}{ll}
\wedge & - \text { Conjunction symbol } \\
v & - \text { Disjunction symbol } \\
\supset & - \text { Implication } \\
\equiv & - \text { Equivalence } \\
\sim & - \text { Negation } \\
\bar{P} & - \text { Also negation } \\
(x) & - \text { Universal quantificaion } \\
\vdash, \nvdash & - \text { Symbols for provabity and non-provability } \\
R\left(W_{1}, W_{2}\right) & - \text { The resolvents of formulae } W_{1} \text { and } W_{2}[13]
\end{array}
$$

## Mathematical Relations: ${ }^{[6]}$

## ALPHA, BETA and TAU

- Relations defined in section C
$\mathrm{R}^{\mathrm{n}} \quad$ - Composition of relation $\mathrm{R}, \mathrm{n}$ times
$\mathrm{R}^{+} \quad$ - Transitive closure of relation $R$
$R^{*} \quad-\quad$ Reflexive transitive closure of relation $R$

General Usage:

$$
\begin{array}{ll}
\equiv & \text { - read "is defined as", in definitions and algorithms } \\
\bigcirc \quad \text { - computational complexity of an algorithm (order complexity) }
\end{array}
$$

