

Silicon photonic resonator sensors and devices

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ABSTRACT

Silicon photonic resonators, implemented using silicon-on-insulator substrates, are promising for numerous applications. The most commonly studied resonators are ring/racetrack resonators. We have fabricated these and other resonators including disk resonators, waveguide-grating resonators, ring resonator reflectors, contra-directional grating-coupler ring resonators, and racetrack-based multiplexer/demultiplexers.

While numerous resonators have been demonstrated for sensing purposes, it remains unclear as to which structures provide the highest sensitivity and best limit of detection; for example, disc resonators and slot-waveguide-based ring resonators have been conjectured to provide an improved limit of detection. Here, we compare various resonators in terms of sensor metrics for label-free bio-sensing in a micro-fluidic environment. We have integrated resonator arrays with PDMS micro-fluidics for real-time detection of biomolecules in experiments such as antigen-antibody binding reaction experiments using Human Factor IX proteins. Numerous resonators are fabricated on the same wafer and experimentally compared. We identify that, while evanescent-field sensors all operate on the principle that the analyte's refractive index shifts the resonant frequency, there are important differences between implementations that lie in the relationship between the optical field overlap with the analyte and the relative contributions of the various loss mechanisms.

The chips were fabricated in the context of the CMC-UBC Silicon Nanophotonics Fabrication course and workshop. This yearlong, design-based, graduate training program is offered to students from across Canada and, over the last four years, has attracted participants from nearly every Canadian university involved in photonics research. The course takes students through a full design cycle of a photonic circuit, including theory, modelling, design, and experimentation.

Keywords: silicon photonics, lab-on-a-chip, microfluidics, evanescent optical field sensors, optical waveguides, disk resonators, ring resonators, slot waveguides

1. INTRODUCTION

Silicon nanophotonic devices have great potential as highly integrated, low-cost biosensors for medical, point-of-care (POC) and home healthcare diagnostic applications. Recent advances in the silicon photonic biosensor literature have demonstrated clinically relevant sensitivities, and an expanded repertoire of biocompatible chemistries capable of interrogating a variety of biological molecules. Additionally, by leveraging existing CMOS fabrication processes, silicon photonic sensors offer significant advantages in economies of scale over traditional biosensing platforms, allowing for the integration of thousands of sensors on a single millimetre-scale chip. These sensors are poised to displace traditional assays that rely upon multi-step liquid handling processes, significant user intervention, and cumbersome bench-top instrumentation. However, numerous challenges must be overcome to realize a fully integrated silicon photonic biosensing platform, including understanding the optimal sensor characteristics, fluidic and analyte control and on-chip lasers and detectors. This paper discusses important sensor performance metrics in aqueous environments similar to saliva, serum or blood, essential for medical diagnostic applications.

Evanescent field sensors such as Surface Plasmon Resonance (SPR) or planar waveguide based sensors are amongst the most popular optical detection techniques for sensitive and label free biomolecular detection.¹ Compared to other sensing methods, optical sensors methods have the advantages of high sensitivity, no physical contact between sensor and detector, immunity to electromagnetic interference, and multiplexed interrogation. Waveguides with dimensions smaller

than the free-space wavelength of light have a strong evanescent field at the waveguide surface extending a few hundred nanometers into the surrounding media. Any interaction with molecules in proximity or surface bound will change the effective refractive index of the guided mode, which leads to a shift in the optical spectrum of the device. These sensors have shown promise for real time detection of biomolecules because of their sensitivity towards surface binding events.

In the case of a straight waveguide-based sensor, such as a Mach-Zehnder, the interaction is limited by the physical length of the sensing waveguide. The degree of interaction of the evanescent field and the sample for a ring resonator is limited by the number of roundtrips by the light inside the ring and the footprint of the sensing area can be reduced without losing sensitivity. In general, high quality factor (Q) resonators are advantageous for reduced spectral noise of the sensor,² leading to an improved detection limit.

Optical sensors based on ring and racetrack resonators have been proposed and developed using a variety of materials and for a variety of applications such as chemical sensing^{3,4} and sensing of biological molecules such as antibodies or antigens.⁵⁻¹⁰ In particular, the optical, label-free detection of biomolecules is a topic of considerable interest.^{11,12} The sensitivity of a ring resonator is dependent on the overlap of the evanescent field and the sample.² In a strip waveguide most of the field is contained inside the core and only a small portion propagates outside in the media. Most experiments have focused on TE-like polarized waveguide modes, likely since low loss TE waveguides have been available.¹³ However, the TM-like waveguide mode has been shown to offer 3X improved sensitivity (S, nm/RIU)¹⁴ as compared to the TE mode since it has a larger evanescent field component above the waveguide.

To enhance the sensitivity, several alternative resonator structures have been proposed and demonstrated. Slot waveguide resonators^{4,15-19} have shown even further enhanced sensitivity since there is much more optical field contained in the fluid. Other structures proposed and/or demonstrated include disk resonators,^{20,21} disk resonators containing a fluorescent material,²² 1D photonic crystals with holes in waveguide,²³ 2D photonic crystals, and Bragg grating cavities.²⁴ Ring sensors have also been integrated on the end of an optical fibre.²⁵

There has been significant interest in integrating optical sensors with microfluidic channels specifically for the detection of bio-species as well as other molecules.²⁶ Several groups have integrated ring resonator sensors with microfluidic channels,^{7,8} including multiplexing the slot-ring resonator sensors such that only one optical input is used for multiple sensors.^{8,27} Resonator sensors have been arranged in folded-waveguide configurations to make the best possible use of space on the optical device.²⁸ To advance biomedical applications, inkjet printing of chemicals²⁹ on the resonant sensors has been demonstrated.

1.1 Biomedical Applications of Silicon Photonics

Silicon photonic microring resonators, like those described previously, show great promise as label-free sensing and analysis tools in biomedical research, drug development, homeland security, food safety, environmental monitoring and healthcare in POC and low-resource settings.³⁰ Notably, the sensitivity and multiplexing capability of silicon photonic biosensors has advanced to the point where the technology is now competitive with the enzyme-linked immunosorbent assay (ELISA), the current gold standard for clinical assays. Conventional ELISAs utilize a multi-well microtiter plate containing immobilized antibodies that bind to a specific analytes of interest. ELISA-based analysis depends upon multiple time-consuming rinse cycles, the consumption of a significant volume of reagent, and the addition of an enzyme-labeled antibody for optical detection via formation of a chromophore or chemiluminescent reaction. While sensitive and reliable at clinically relevant levels, the ELISA involves costly reagents and a skilled operator, rendering it impractical for distributed, low-resource, and home healthcare settings. Label-free biosensors have been investigated as a competitive alternative to the ELISA.¹ Similar to the ELISA, label-free biosensors leverage a functionalized surface to selectively capture target species. However, unlike ELISA, label-free sensors directly detect the presence of analyte without additional reagents or labels, eliminating the need for multiple rinse steps and a secondary probe, and dramatically decreasing assay time.

In medicine, accurately diagnosing a disease state often requires the detection and quantification of multiple biological markers (proteins, nucleic acids, lipids, carbohydrates and small organic biomolecules). Silicon photonic sensors facilitate simultaneous multi-analyte detection by interrogating matrixed sensor arrays on a single chip, referred to as multiplexed detection.³¹ For example, a single-marker assay for prostate-specific antigen (PSA) to detect prostate cancer possessed a meager 65% sensitivity and 35% specificity.³² By contrast, a multi-marker protein panel improved the sensitivity and specificity to 83% and 97%, respectively. This result highlights the inherent advantage of multiplexed detection in medical diagnostics.

While a fully integrated, label-free silicon photonics biosensor has yet to be realized commercially, the technology has established its utility for medical diagnostics at clinically relevant sensitivities.¹ Washburn et al. have demonstrated simultaneous analysis of multiple biomarkers on a single microring sensor array, successfully quantifying PSA, α -fetoprotein (AFP), carcinoembryonic antigen (CEA), tumor necrosis factor- α (TNF- α), and interleukin-8 (IL-8) at clinical concentrations.³³ Like proteins, MicroRNAs (mRNAs) play a role in a variety of disease states, including cancer, heart disease, and central nervous system disorders, and can be used as markers for early disease detection and diagnosis. Using silicon-based photonic sensors, Qavi et al. demonstrated a multiplexed mRNA diagnostic capability by discriminating between single nucleotide polymorphisms of the let-7 family in concentrations of 150 fmol with minimal sample preparation.³⁴ In addition, Ramachandran et al. have reported that whole bacteria can be successfully detected using microring resonators.⁶ These examples illustrate the transformative potential of label-free silicon-photonics sensors.

At present, the aforementioned biosensing examples rely on external lasers and detectors, which limit their application for distributed multiplexed sensing and diagnosis. On-chip detectors capable of interrogating thousands of functionalized sensors are necessary to realize a fully distributable diagnostic device. Towards this goal, Yan et al. recently demonstrated an optical sensor fabricated in a commercially available 0.35 μm CMOS technology with integrated electronic detectors.³⁵ Kirk et al. developed a method to rapidly functionalize individual rings in a 50 x 50 μm footprint using a commercially available non-contact piezo printer that can be scaled to print multiple chips in parallel.²⁹ Finally, Hochberg et al. reported on the benefits of a shared-wafer fabrication consortium which offers low-cost prototyping through commercially available CMOS chip fabrication facilities.³⁶ These strategies, coupled with low-cost LED light sources point to the significant role that a fully integrated label-free, silicon-based nanophotonic diagnostic device could play in both POC diagnostics and distributed healthcare.

1.2 Sensor Performance – Criteria

This section describes the most important performance criteria which are useful for comparing different sensor geometries. The metrics are based on the work of White² and Yoshie³⁷ particularly for micro-resonator sensors. The most important are:

1. Sensitivity (S), which is the slope of wavelength shift versus bulk refractive index unit change [nm/RIU], also sometimes known as Responsivity (R). In a resonator, the wavelength shift is described by:³⁸

$$\frac{\Delta\lambda}{\lambda} = \frac{\Delta n_{\text{fluid}}}{n_g} \frac{\partial n_{\text{eff}}}{\partial n_{\text{fluid}}} \quad (1)$$

The contributions to the shift are from: a) the shift in the analyte's index of refraction (Δn_{fluid}), b) the material and waveguide dispersion (n_g) – a change in wavelength causes a further change in effective index, and c) the change in index slightly changes the mode profile resulting in the mode's effective index change (susceptibility, $\partial n_{\text{eff}}/\partial n_{\text{fluid}}$). The same effect is found in the temperature dependence of waveguide-based resonators.³⁹ In high-contrast silicon photonic devices, n_g is typically 4-5, and $\partial n_{\text{eff}}/\partial n_{\text{fluid}}$ is approximately 0.15 (for strip and ridge waveguides). In contrast free-space propagation would have $\partial n_{\text{eff}}/\partial n_{\text{fluid}} = 1$.

The sensitivity is defined as

$$S = \frac{\Delta\lambda}{\Delta n_{\text{fluid}}}, \quad (2)$$

and the normalized sensitivity (useful for comparing different wavelength resonators) is

$$S' = \frac{S}{\lambda} = \frac{\Delta\lambda}{\lambda} \frac{1}{\Delta n_{\text{fluid}}}. \quad (3)$$

2. Q factor, which is the number of oscillations before the energy has decayed to the 1/e value. A high Q-factor means that light is present in the resonator longer and interacts more with the analyte. It is also advantageous in reducing the spectral noise of the sensor,² which improves the limit of detection. The resonator Q can be found from the total distributed loss of the resonator (in m^{-1} , in dB/m, or in terms of the material complex index of refraction, $n + ik$),

$$Q = \omega_0 \frac{\mathcal{E}}{d\mathcal{E}/dt} = \omega_0 \tau_p = \frac{\omega_0}{\alpha_{[m^{-1}]} \cdot \frac{c}{n_g}} = \frac{2\pi \cdot n_g}{\lambda_0 \cdot \alpha_{[m^{-1}]}} = \frac{2\pi \cdot n_g \cdot 4.34}{\lambda_0 \cdot \alpha_{[dB/m]}} = \frac{n_g}{2 \cdot k}. \quad (4)$$

These losses originate from waveguide scattering, material absorption (waveguide and analyte), waveguide radiation loss, mode mismatch losses, etc. Equation 4 is useful to identify the intrinsic Q for a resonator with a particular waveguide propagation loss, e.g., 3 dB/cm waveguides yield intrinsic Q values of 258,000 at 1550 nm; if this resonator was critically coupled, the Q value is reduced by a factor of two and becomes 129,000.

3. Limit of Detection (LOD, or Detection Limit, DL) which is the minimum detectable refractive index unit change [RIU]. The detection limit can be defined two ways: 1) change in index corresponding to one resonator linewidth (Δn_{min}) – this is useful to compare the intrinsic device performance, and 2) a system detection limit ($\Delta n_{min,sys}$) which corresponds to the index change for a standard deviation in the measurement noise (here, the wavelength reading noise). The highest performing systems have a detection limit on the order of 10^{-7} RIU.⁴⁰

The limit of detection is calculated by³⁷

$$\Delta n_{min} = LOD = \frac{1}{QS'} \quad (5)$$

4. The limit of detection can also be expressed in a biological perspective, e.g., in terms of the adsorbent's thickness.

1.3 Comparison of Experimental Sensitivity and Detection Limit

Here, we compare several silicon photonics evanescent field sensors operating at 1550 nm. We compare the intrinsic detection limit, i.e., the change in index corresponding to one resonator linewidth (Δn_{min}). This comparison allows one to compare the intrinsic device performance, independent of the read-out method, electronics and noise. The comparison includes previous literature on ring/racetrack resonators,^{5,10,25,41} slot resonators,⁷ and 1D photonic crystals.²³ It also includes the experimental results presented in Section 2. For each device, the normalized Sensitivity (S') and Q are identified (in water) and the results are plotted in Figure 1.

The data points with the highest limit of detection are found towards the upper-right of the plot, and the limit of detection is identified by the contour lines using Equation 5. The highest reported limit of detection is for the TM-like mode strip waveguide,⁴¹ with the slot waveguides and photonic crystals having the worst performance.

Since this plot is for volume index of refraction changes, not included is the single-molecule detection work of Vahala²¹ where the high-Q cavity results in locally heating the molecule and inducing a thermo-optic effect which results in enhanced wavelength shifts. SPR sensors⁴² are also not included. They work on the same principle as resonators, namely an evanescent field interacts with the sample, but the evanescent field originates from a surface plasmon in a metal film. Comparing dielectric and SPR sensors: a) SPR typically has a slightly longer field decay (200 nm vs. 100 nm), b) sensitivities are much higher, but the limit of detection is similar. As an example of a commercial SPR system, the Biacore X has a noise of 0.6 RU (where 1 RU is defined as 10^{-6} RIU),⁴³ hence a detection limit of 0.6×10^{-6} RIU.

2. EXPERIMENTAL RESULTS ON THE SAME WAFER

Silicon photonic devices were fabricated using 193 nm lithography by IMEC accessed via CMC Microsystems and ePIX-fab. All designs described in this section were fabricated on the same wafer to aid in the direct comparison of the resonators. SEM images of the fabricated devices are shown in Figs. 3, 5, and 6.

2.1 Lab-on-a-chip, PDMS Microfluidics

The concept of a lab-on-a-chip combines sample handling and analysis in one single chip, thereby offering the possibility of a portable analysis platform. Picoliter sample volumes can be handled inside micrometer scale fluidic channels using valves and pumps integrated into silicon or polymer chips.⁴⁴ It is of great interest to include sensor technology into these lab-on-chip devices to automate parallel processing and therefore lower cost and increase throughput. Ksendzov et al. clamped a flow cell down onto the sensor chip.⁴⁵ They achieved sealing by using an O-ring and pressure. However they are not able to expose individual resonators with different analytes. Washburn et al. and Luchansky et al. used a laser cut Mylar gasket aligned over top of the microring arrays to define microfluidic channels.^{1,9} They closed the channels off with a Teflon lid and sandwiched the different layers between aluminum chip holders. Because mass transport is diffusion limited, they are not suitable to determine dynamics of fast reactions, e.g. binding events of proteins. Moreover, in order to be able to run several experiments with different analytes or different concentrations in parallel individual resonators need

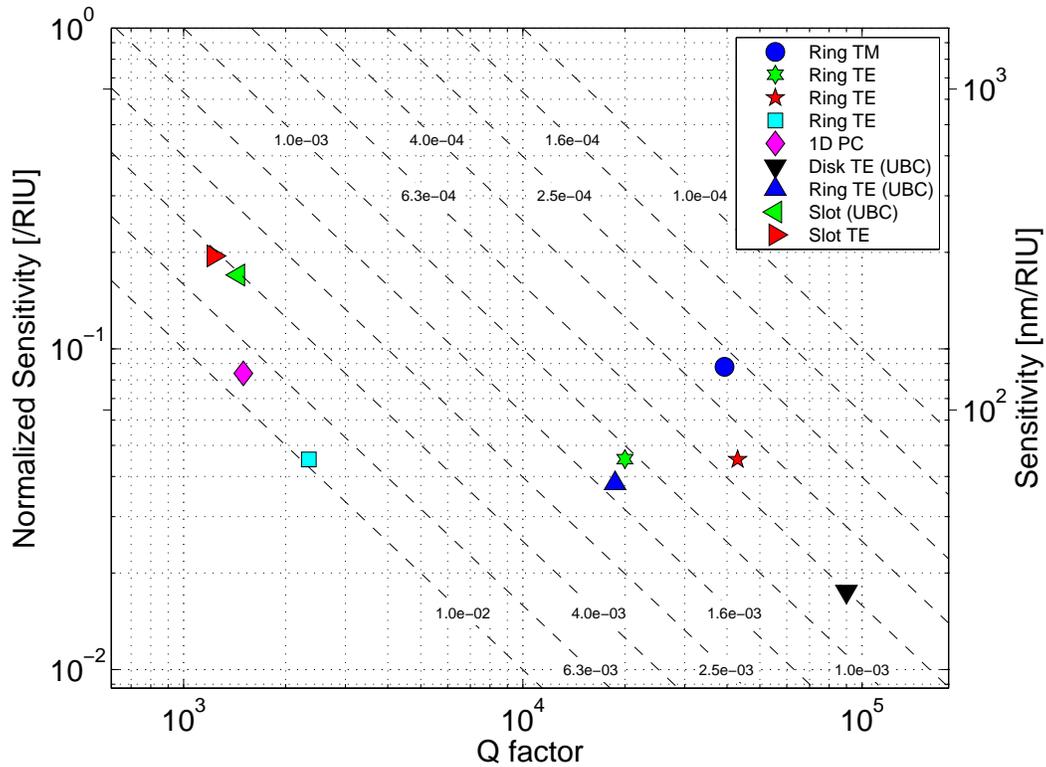


Figure 1. Summary of experimental results for Limits of Detection (LOD) for linear 1550 nm silicon photonic biosensors. Here, **LOD is calculated for a noise equivalent to one resonator linewidth**, which is useful to compare the intrinsic device performance. The diagonal lines correspond to LOD values of $\Delta n_{min} = 10^{-2}$ to 10^{-4} . The right y-axis is the sensitivity, Eq. 2, while the left y-axis is the sensitivity normalized to the wavelength, Eq. 3.

to be addressed and exposed. Carlborg et al. used a microfluidic channel network in poly(dimethylsiloxane) (PDMS), with a separate fluid channel to each sensor for sample delivery.⁸

PDMS is the most widely used polymer in the field of microfluidics. It is a biocompatible, transparent, rubber-like polymer and can be easily patterned using soft lithography, a well established fabrication method.⁴⁶ The mold masters were fabricated with standard photolithography techniques on SU-8 2075 (MicroChem, USA). Through replica molding the patterns were transferred onto PDMS. The uncured PDMS (Sylgard 184, Dow Corning USA) was poured onto the mold master to a thickness of about 1 cm, degassed to remove air bubbles, and cured at 80°C for 2h on a hotplate. The hydrophobic surface properties can be altered in an oxygen plasma by replacing some of the surface methyl groups (CH₃) by a hydroxyl groups (-OH). This activated surface can form covalent siloxane bonds (Si-O-Si) when in contact with glass or silicon substrates, forming an irreversible seal. However, we have found that we obtain sufficient sealing between the silicon chips and PDMS by performing reversible bonding. After punching access holes for the fluidic inlet and outlets the PDMS layer and the resonator substrate were aligned using a stereo microscope and bonded to each other. The PDMS channels were 100 μm wide, 100 μm tall, with a pitch of 300 μm . The bonded chips and measurement setup is shown in Fig. 2.

2.2 Optical Setup

The optical test setup for the fabricated nanophotonics chips consisted of a tunable laser source (Agilent 81682A, Agilent Technologies, Inc., USA) with an output wavelength range from 1460 nm to 1580 nm; a polarization maintaining optical fibre was aligned with the fibre grating coupler to inject light into the SOI waveguides; the output light was collected with a single-mode optical fiber and measured with an optical power sensor (Agilent 81635A, Agilent Technologies, Inc., USA); the temperature of the substrate was kept constant with a Peltier element and a temperature controller (LDC501, Stanford Research System, USA) in a closed feedback loop configuration (typically 1-10 mK stability). A microscope system was

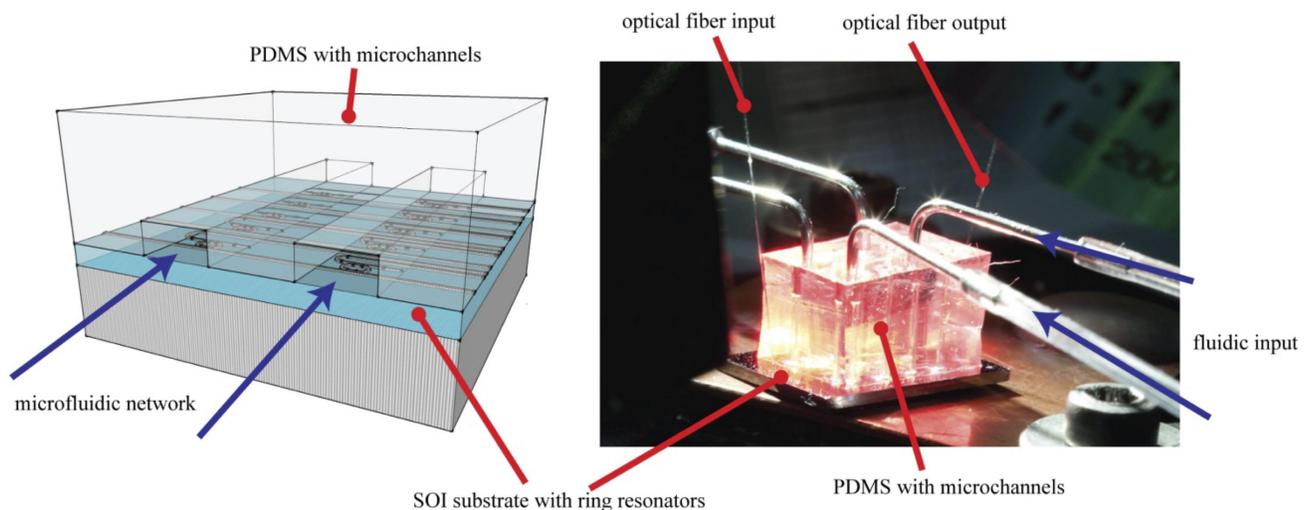


Figure 2. The measurement setup:⁴⁸ the optical input fibre is connected to a tuneable laser source with wavelength at around 1550 nm and the output optical fibre is connected to an optical power sensor. The measurements are performed on a temperature controlled stage. Fluidic tubing are connected to a syringe pump.

used for fibre alignment. A MATLAB script was used to sweep the laser wavelength in order to acquire the transmission spectra for the various devices (sweep interval 20s with 10,000 data points).

For calibrating the sensors (sensitivity, Q), fluids of varying refractive index were flowed through the microfluidic channels under positive pressure, exposing the resonators to different immersion media refractive indices. Varying concentrations of glycerin in water were used as these varying known refractive indices.⁴⁷ The positions of the resonance peaks were dynamically tracked by continuously sweeping the laser and curve fitting the spectrum. The wavelength tracking also proves useful when employing the resonators for biosensing applications, as it provides useful visual feedback when attaching proteins or antibodies to the resonators and is helpful to identify problems in the system (for example, a bubble in the channel).

2.3 Ring resonators

Racetrack resonators are designed following Rouger et. al⁴⁹ and using the Lumerical MODE Solutions eigen-mode solver.⁵⁰ The resonators were designed for critically-coupled double-bus configurations with parameters calculated using the MODE Solutions simulated material losses, the MODE Solutions simulated bend losses (radiation and mode-mismatch from straight to bent waveguide), and the straight-waveguide scattering losses from previous findings as well as the literature (4 dB/cm for the strip waveguides) and 12 dB/cm for the slot waveguides.⁷ The round-trip resonator losses were used to calculate the coupling lengths, where the coupling coefficients were calculated from the effective indices of the coupler super-modes.

Devices with both strip and slot waveguides were fabricated. Two of the fabricated chips were analyzed by SEM imaging and FIB cross-sectioning, as shown in figure 3. FIB cross-sectioning showed that the waveguides were narrower at their tops, with sidewall angles of approximately 9.5° .

2.4 Slot waveguide ring resonator

Mode profiles and modelling results for the slot waveguide design are shown in Fig. 4. Figure 4d presents the simulated immersion medium index sensitivity versus simulated waveguide base width. This is simulated to take into account the IMEC exposure dose sweep that was applied across the wafer, and which results in changes in the waveguide thickness. The changes also result in changes in the slot waveguide gap, which leads to changes in the sensitivity. The sensitivity decreases with increasing waveguide width, as a result of the increasing optical confinement of the mode within the silicon and a decreasing slot width. The measured sensitivity of 345 nm/RIU is comparable to the 298 nm/RIU reported for a similar design (with a similarly low Q factor of 330) in SOI by Claes et al.⁷

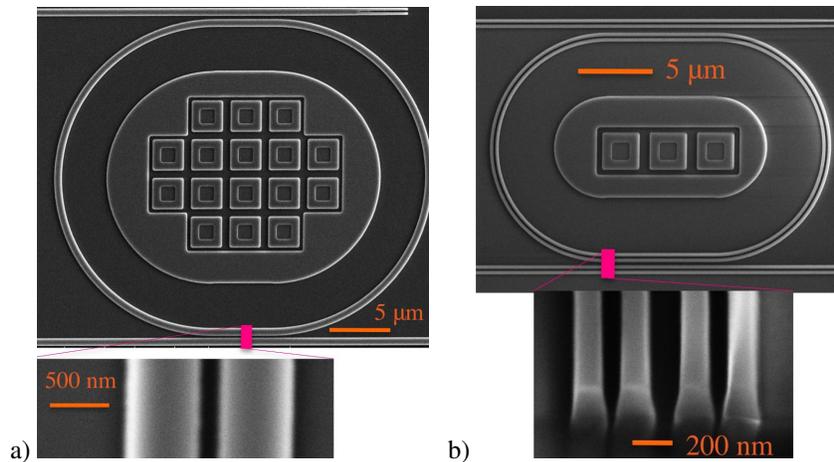


Figure 3. a) SEM images of strip waveguide ring resonators. The inset shows an SEM image of the highlighted coupler region. b) SEM images of slot waveguide ring resonators. The inset shows an SEM image of an FIB cross-section of the through port coupler; the slots in these waveguides are well-defined, all the way through the 220 nm of silicon.

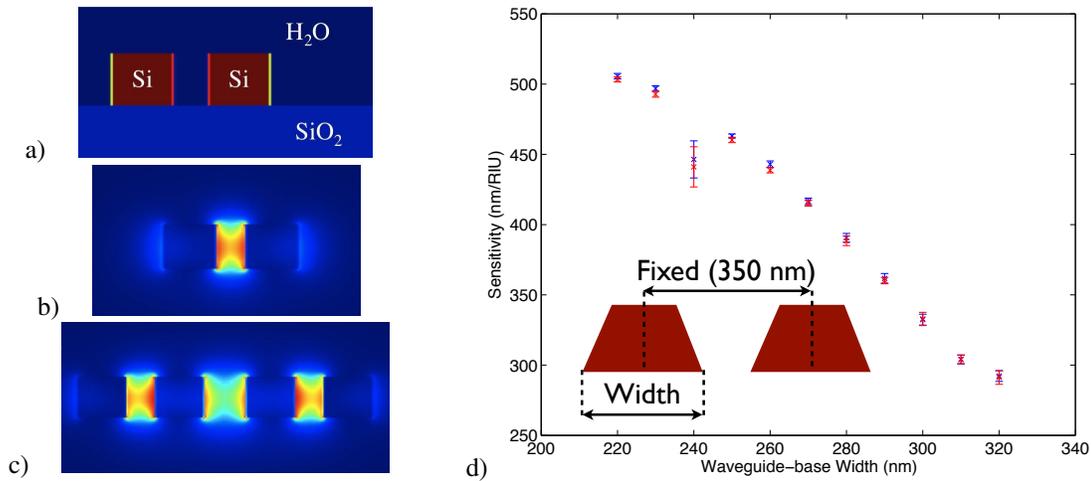


Figure 4. Simulations for the slot waveguide geometry: b) Material index profile. c) Electric field distribution for straight waveguide. d) Coupling super-mode 1 between parallel identical slot waveguides. d) Simulation results of immersion medium refractive index sensitivity vs. waveguide width for slot waveguide racetrack resonators. The blue points plot the sensitivity to a change from 0% to 2% glycerine, while the red points plot the sensitivity to a change from 2% to 4% glycerine.

2.5 Bragg Grating resonators

Bragg gratings, as well as quarter-shifted grating cavities were fabricated on the wafer.⁵¹ It is expected that the sensitivity of the grating will be equivalent to its straight waveguide counterpart.²⁴ The quarter-shifted Bragg grating resonators demonstrated high-Q values of 100,000 with air cladding. The transmission spectrum of the device and SEM image are shown in Fig. 5.

2.6 Disk resonators

Ultra-compact, high-Q disk resonators have been theoretically investigated and experimentally demonstrated.⁵²⁻⁵⁴ We use a similar geometry and size of disk⁵⁴ in this investigation.

We discuss two approaches to modelling disk resonators which we have verified to have excellent agreement. The first method is to do a full 3D FDTD simulation of the entire disk.⁵⁵ This is possible since the geometry of the disk is relatively small. The objectives of the simulation are: a) find the resonant modes of the disk, for a given polarization, and b) find the sensitivity (nm/RIU). The simulation includes the disk, the oxide, and the water, surrounded by PML boundary conditions.

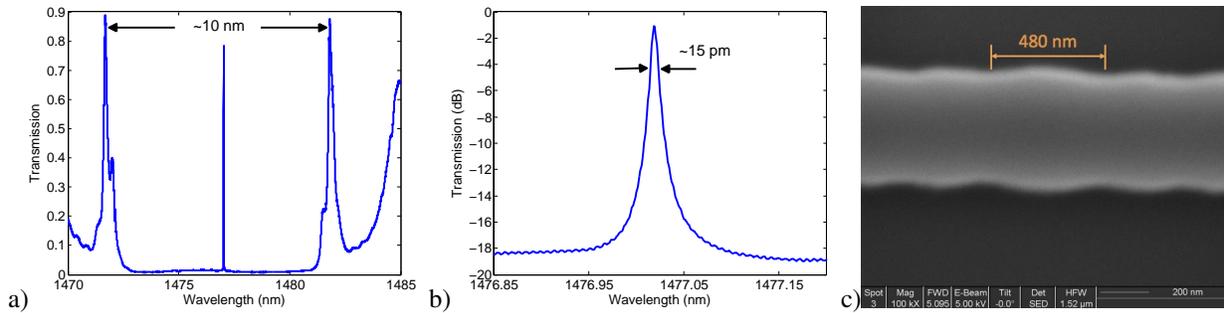


Figure 5. a) Measured transmission spectrum of the quarter-wave phase-shifted gratings, (b) enlarged plot around the transmission resonance, c) SEM image of the fabricated device, showing the quarter-shifted section.

The disk is excited by several dipole sources placed inside the disk. In order to find the sensitivity, we perform several FDTD simulations with a variation of cladding index of refraction. We then inspect the spectrum of the cavity and observe the shift in the cavity modes (nm), versus the applied changes in refractive index (RIU).

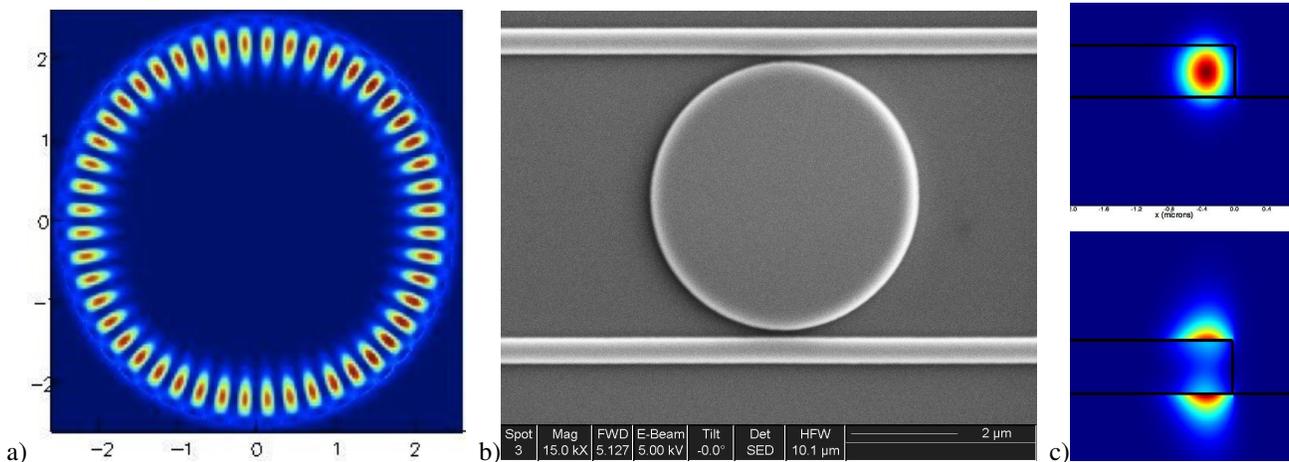


Figure 6. a) 3D FDTD calculation showing the top-view TE mode profile of a $2.5 \mu\text{m}$ disk. Counting the number of nodes (48) indicates that this is mode #24. b) SEM image of the disk. c) Mode calculation for the cross-section of the disk, TE mode (top), TM mode (bottom). All simulation plots are for the E-field intensity.

The second approach is similar to a conventional waveguide mode calculation,⁵⁰ where we calculate the disk's cross-section mode profile, effective index, group index and loss for the lowest order TE and TM modes as a function of wavelength. The radius of the disk is included in the simulation by defining the bend radius as the actual radius of the disk. The advantage of this approach is that a much finer mesh can be employed since it is a 2D simulation, hence the accuracy can be improved. Similar to the 3D FDTD simulations, we vary the cladding index and record the shift in effective index. Next, we calculate the resonant modes by using simple Fabry-Perot theory, namely we find solutions where the round-trip phase is an integer multiple of 2π , using $2\pi M = 2\pi n_{\text{eff}}(\lambda)L/\lambda$, where $L = 2\pi r$ is the circumference of the disk. We re-write this as

$$M \frac{\lambda}{2\pi r} = n_{\text{eff}}(\lambda) \quad (6)$$

and plot the results of the left-hand-side and right-hand-side of the equation in Figure 7a. The intersection of the $n_{\text{eff}}(\lambda)$ line with the mode number lines provides the solution(s) to the equation and yields the resonant wavelength(s). This technique can further be used to find the modes of different sized disks by recalculating the n_{eff} versus wavelength graphs and re-plotting the above.

The loss of the each mode is also calculated by the mode solver, including the water absorption. For TM modes, the

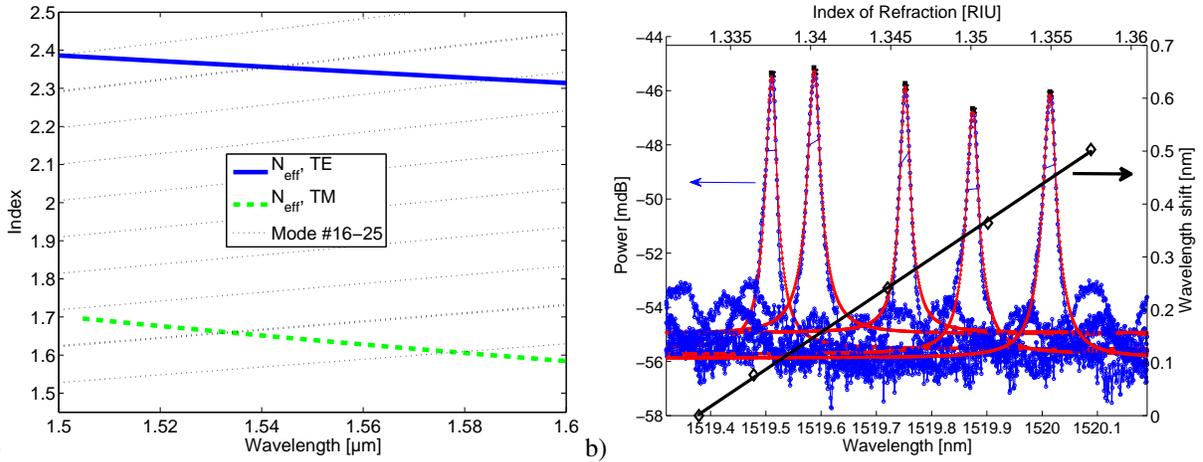


Figure 7. a) Effective index of the 2.5 μm disk resonator modes versus wavelength. Upward trending lines are the required effective index values to achieve a resonant condition for mode numbers $m = 16$ up to $m = 25$. b) Experimental performance of a 5 μm disk resonator in water. The optical spectra (bottom and left axes) for the resonator show a Q of between 80,000 and 100,000. Varying the water index of refraction (top axis) by changing the concentration of glycerine changes the resonant wavelength (right axis); the sensitivity is 27.1 nm/RIU.

radiation loss cannot be neglected.⁵⁴ In particular, the TM mode 2.5 μm disk is impractical since the radiative losses are 600 dB/cm. Hence, larger disks are required for TM operation.

Experimental results for a disk resonator are shown in Figure 7b. The Q value in water is approximately 90,000, while the sensitivity is 27.1 nm/RIU.

3. DISCUSSION AND ANALYSIS

3.1 Fundamental Limit for Water-Based Sensors

We are interested in the fundamental limit of detection based on the water absorption and index change. We consider an ideal Fabry-Perot cavity and assume that the light travels entirely in the water, with no other loss mechanism other than water absorption. In this case $\partial n_{\text{eff}}/\partial n_{\text{fluid}} = 1$. Using Eq. 1, this yields

$$\frac{\Delta\lambda}{\lambda_0} = \frac{\Delta n_{\text{fluid}}}{n_g} \quad (7)$$

or a sensitivity at $\lambda = 1550$ nm of

$$S_{\text{ideal}} = \frac{\Delta\lambda}{\Delta n_{\text{fluid}}} = \frac{\lambda_0}{n_g} = 1550/1.33 = 1165 \text{ nm}/RIU \quad (8)$$

Note that this fundamental limit applies to dielectric evanescent sensors. It also applies to grating-based SPR sensors,⁵⁶ but not prism-coupled ones (which can achieve much higher nm/RIU values).

Applying Eq. 4 for water absorption at 1550 nm (9.6 cm^{-1}) we find the intrinsic Q is limited to 5,500. The intrinsic Q for water is plotted versus wavelength in Fig. 8a. The Q is calculated from the water absorption spectrum⁵⁷ using Eq. 4. This assumes that the light travels entirely in the water, as in an ideal Fabry-Perot cavity. Hence, $S=1165$ nm/RIU, and the limit of detection is $2.4 \times 10^{-4} RIU$. This fundamental limit is included in Fig. 9. The intrinsic limit of detection is plotted versus wavelength in Fig. 8b, using Eqs. 4, 5 and 8. Also included is a curve with additional waveguide scattering loss of 5 dB/cm at 1550 nm (based on previous measurements⁵⁸), scaled using Rayleigh's $1/\lambda^4$ dependence for other wavelengths. Finally, assuming a typical³⁷ system readout sensitivity improvement of 100X, the system's limit of detection would be $2.4 \times 10^{-6} RIU$ at 1550 nm, and is plotted in Fig. 8b versus wavelength.

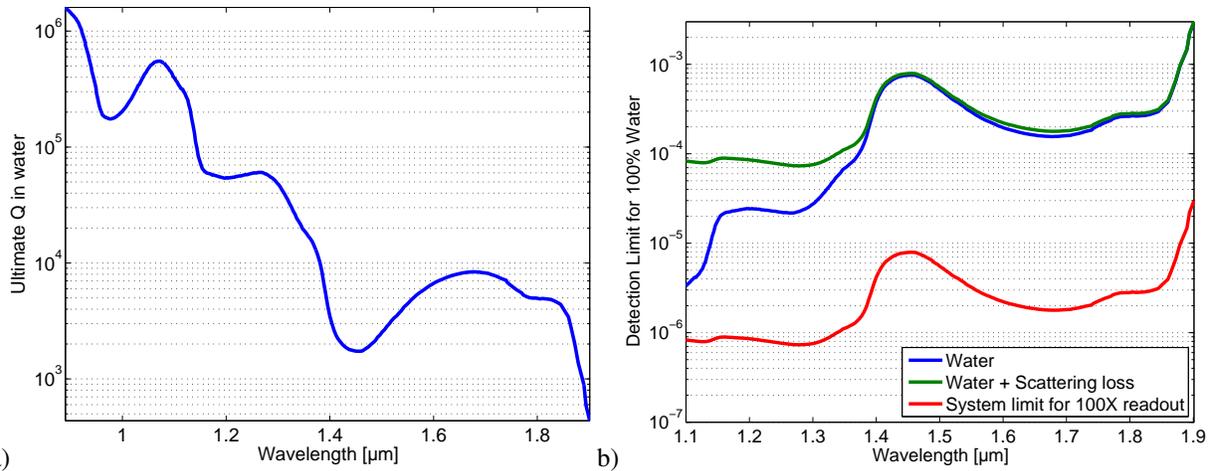


Figure 8. a) Maximum resonator Q limited by optical absorption from water. b) Highest predicted limits of detection for water absorption-limited sensing. Waveguide scattering is subsequently added and assumed to contribute 5 dB/cm loss at 1550 nm, and scale as $1/\lambda^4$ for other wavelengths. Finally, the system detection limit is shown, assuming a wavelength readout precision 100X better than the resonator linewidth. Note that silicon optical absorption, not included in here, dominates over water absorption for wavelengths $< 1.1 \mu\text{m}$ and is negligible for wavelengths $> 1.1 \mu\text{m}$.

Table 1. Summary of silicon photonic sensors and their performance

Experimental results					
Sensor type	Geometry	Q (in water)	S [nm/RIU]	S' [RIU]	Δn_{min}
Ring ⁴¹	TM, 260x450nm strip	39,299	135	0.088	2.9×10^{-4}
Ring ⁵	TE, 220x500 nm	20,000	70	0.045	1.1×10^{-3}
Disk	TE, 220x5 μm	90,000	27	0.0175	6.4×10^{-4}

Modelling results: 1550 nm, in water. Coupling losses not included (intrinsic resonator only).

Sensor type	Geometry	Q	dB/cm	FSR [nm]	$\partial n_{eff}/\partial n_{fluid}$	S	S'	Δn_{min}
Ring	TE, 220x500 nm strip	106,719	6.9	up to 6	0.152	56	0.036	2.57×10^{-4}
Ring	TM, 220x500 nm strip	34,500	22.7	up to 6	0.52	179	0.116	2.51×10^{-4}
Disk	TE, 220x2.5 μm	232,854	2.8	45	0.064	27	0.017	2.49×10^{-4}
Slot	TE, 220x550/110 nm	12,822	34	up to 6	0.80	460	0.30	2.63×10^{-4}

3.2 Comparison of Modelling versus Experiments

A summary of selected published resonator sensor results, together with the experimental and modelling results presented in this paper, are given in Table 1. Modelling of the strip waveguide ring resonator (TE and TM modes), disk resonator (TE and TM mode), and slot waveguide ring resonator (TE mode) were conducted using the methodology described in Section 2.6. Specifically, we consider an intrinsic resonator, without any out-coupling losses and with side-wall roughness scattering. The parameters of interest are the propagation loss (dB/cm) from the water absorption and radiation losses which determines the Q of the resonator, as well as the sensitivity (S, S') which is found by determining the waveguide susceptibility ($\partial n_{eff}/\partial n_{fluid}$). These values are used to find the intrinsic limit of detection, Δn_{min} . Additionally, the resonator free-spectral range (FSR) is identified.

The most important observation from the modelling results is that all resonators should theoretically have the same limit of detection, under the condition of a fixed wavelength and no scattering losses. The simulated results (S', Q, Δn_{min}) for the various structures are shown in Fig. 9. As shown, all sensors have the same sensitivity of $\Delta n_{min} \sim 2.5 \times 10^{-4}$. This, according to Eq. 5, implies that the fundamental limit of the sensor is that the sensitivity is inversely proportional to the Q factor. Any increase in the sensitivity (e.g., by employing slot waveguides) will simply reduce the Q factor by the same amount. Similarly, high-Q structures (e.g., disks) that do not interact much with water will have a lower sensitivity.

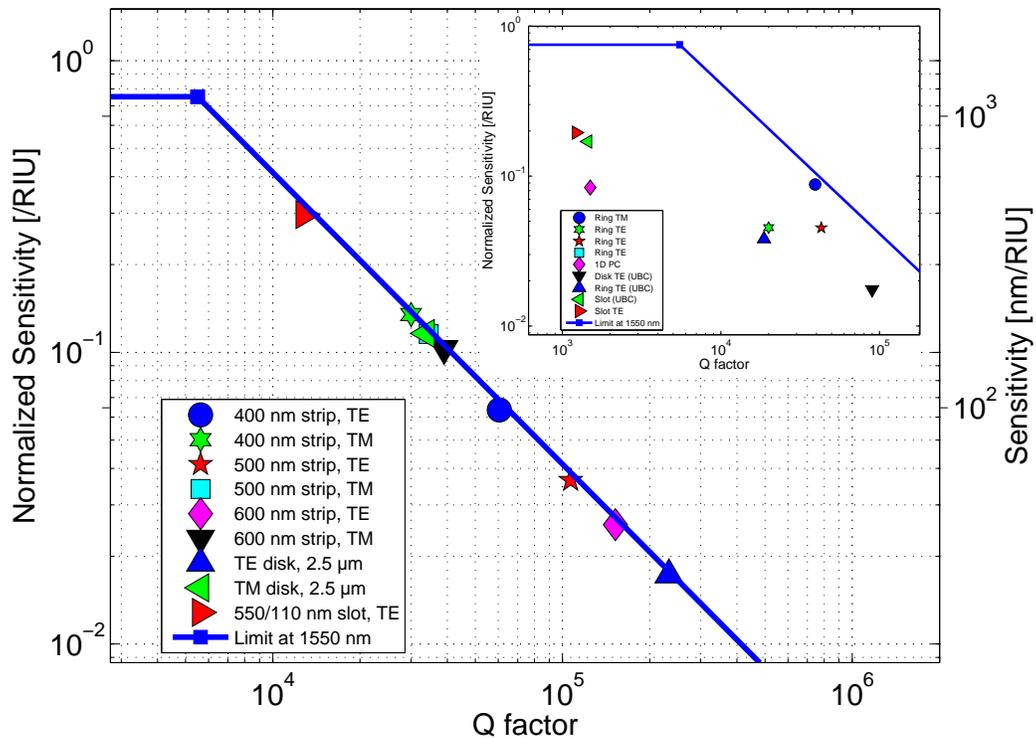


Figure 9. Summary of model results for Limits of Detection (LD) for 1550 nm silicon photonic biosensors, for the various configurations studied in this work (data points). The theoretical maximum based on the water absorption limit is the line, in which the single data point represents light travelling exclusively in water. From this point, two limits are drawn: a) the line to the left of the point is the maximum sensitivity where light has 100% interaction with water, namely $\partial n_{\text{eff}}/\partial n_{\text{fluid}} = 1$, and b) the line diagonally down-right shows that the Q-factor limit due to the water absorption increases as the light interacts less with the water, i.e., $\partial n_{\text{eff}}/\partial n_{\text{fluid}} < 1$. These limits only depend on, respectively: a) the index of refraction of the analyte, b) the optical loss of the analyte, i.e., $n(\lambda) + ik(\lambda)$. **Inset:** Experimental data points from Fig. 1 with the addition of the theoretical maximum lines.

To understand why different resonators have various levels of sensitivity in Fig. 1, we need to consider the additional loss mechanisms in the resonators. The dominant loss in the TE-like mode devices is the side-wall roughness scattering. As a result, devices with a strong field overlap with the sidewall will have significantly increased propagation loss, hence reduced Q, and a reduced limit of detection. This can be quantified by comparing the total propagation losses versus losses induced by the water absorption. Ideally water absorption would dominate to achieve the highest limit of detection. In the case of the slot waveguide resonators, our measured Q values have been 1,450, while the intrinsic Q from water absorption would suggest a Q of over 12,000. Additionally, it is believed that the analyte does not penetrate the slot completely. Hence, S' is slightly reduced, Q is significantly reduced, which leads to a limit of detection, 2.4×10^{-3} , that is 10X lower than theoretically possible.

Meanwhile, the TE disk resonators have a limit of detection of 5.5×10^{-4} , which is only 2X lower than theoretically possible. This is better than the TE mode strip waveguide resonators, and is explained as follows: a) the whispering gallery mode is only confined by one waveguide side-wall, rather than the two in the strip waveguides, hence the scattering losses are reduced, b) the mode-profile has a shape that is more similar to a 600 nm waveguide, and it is known that wider waveguides have lower losses¹³ due to reduced interaction with the side-walls. These two factors contribute to a higher Q factor. The disadvantage is that the electric field interacts less with the analyte, hence lower sensitivity. However, a potential advantage is that the field-analyte interaction is now primarily above the disk, as opposed to on the side of the waveguides as in TE strip waveguides, which may be beneficial for biological applications where the analyte (e.g., virus) can more easily diffuse and adsorb to the top surface.

An interesting observation from Table 1 and Fig. 1 is that some of the demonstrated 1550 nm sensors already measure at the fundamental water absorption limit. Specifically, this was achieved in the system using TM polarization where a

Table 2. Loss mechanisms in silicon photonic sensors. Resonators are assumed to be in isolation. If they were critically coupled, the total Q would be reduced by 2X, hence the limit of detection would be reduced by 2X.

Sensor	$Q_{\text{scattering}}$	Q_{water}	$\frac{Q_{\text{scattering}}}{Q_{\text{water}}}$	dB/cm (scattering)	dB/cm (water)	dB/cm (total)	Predicted Δn_{min}
Ideal, water only	∞	5500	∞	0	43	43	2.4×10^{-4}
Ring TE, 220x500 nm strip	258,000	106,719	2.42	3	6.9	9.9	3.7×10^{-4}
Ring TE, 220x500 nm strip	147,000	106,719	1.4	5^{58}	6.9	11.9	4.5×10^{-4}
Ring TE, 220x500 nm strip	43,000	106,719	0.40	18	6.9	24.9	9.1×10^{-4}
Ring TM, 220x500 nm strip	147,000	34,500	4.3	5	22.7	27.7	3.1×10^{-4}
Disk TE, 220x2.5 μm	124,000	232,854	0.53	–	–	–	7.3×10^{-4}
Slot TE, 220x550/110 nm	58,643	12,822	4.6	12^7	34	46	3.2×10^{-4}
Slot TE, 220x550/110 nm	1,450	12,822	0.12	500^7	34	534	2.6×10^{-3}

large portion of the light is above the waveguide.⁴¹ In this case, the water absorption dominates, and the limit of detection almost matches that predicted in Fig. 9.

In summary, the best device (as quantified by the limit of detection) would have no loss (except for water, and some for sensing itself via couplers) and the light would resonate primarily in the sensing fluid. In the case where the waveguide scattering and radiation losses can be reduced to below the water absorption losses, operating at different wavelengths can also be considered as shown in Fig. 8. With present fabrication technology (scattering loss limited), only the TM mode resonators would benefit from a reduced water absorption from a change in wavelength.

It is interesting to consider whether there exist methods of beating this limit. For example, high group index structures such as Bragg gratings, photonic crystals, or plasmonic devices, will enable the light to travel more slowly through the water hence potentially have sensitivities higher than predicted by Eq. 3. However, this comes together with correspondingly higher optical loss, hence reduced Q. Indeed, SPR prism-coupled sensors have much higher sensitivity, albeit with a very broad linewidth (e.g., over 100 nm), and ultimately their limits of detection are comparable to these considered here (the different wavelength used in SPR prevents the direct comparison with this analysis).

3.3 Readout

Until now, the discussion has focused on a limit of detection determined by the linewidth of the resonator. This was done specifically to compare the intrinsic performance of difference resonators, independent of the signal processing and detection methods. Measurement of the resonant wavelength typically involves measuring a spectrum. How the resonant wavelength is measured will impact the precision. This is particularly true when the spectrum contains amplitude (and wavelength) noise. Curve fitting the spectrum to an analytic transfer function is a method in which the algorithm takes into account contributions from the entire spectrum, rather than simply finding the peak. Similar to averaging, this improves the eventual signal-to-noise ratio by \sqrt{N} , where N is the number of data points in the spectrum. If the noise is low enough, this technique can result in an interpolation of the resonant wavelength and achieve a wavelength resolution even below the original data sample spacing. Optical spectrum processing has been applied to silicon photonic sensors, and has resulted in a wavelength measurement precision that is 10s to 100s of times smaller than the resonator linewidth.³⁷ For example, the Genolyte system achieves a 3σ wavelength measurement noise of 0.2 pm.¹⁰ Compare this to a typical 500x220 nm strip-waveguide ring resonator with a Q of 30,000 in water at 1550 nm, with a linewidth of $\Delta\lambda_{1/2} = 50\text{pm}$, this implies an enhancement factor of over 250X in the spectrum readout as compared to the resonator linewidth used in the intrinsic limit of detection defined in Eq. 5.

The limit of detection analysis can also be applied to temperature sensors. Assuming spectral sweep measurement can result in a 100X higher wavelength measurement precision than the resonator linewidth (typical³⁷), and for a resonator with a Q=100,000, and a sensitivity of $S = 0.08\text{nm}/K$,⁴⁹ the thermal detection limit is comparable to thermistors:

$$DL = \frac{\lambda}{100 \cdot Q \cdot S} = \frac{1550 \times 10^{-9}}{100 \cdot 10^6 \cdot 0.08 \times 10^{-9}} = 2\text{mK}$$

3.4 Biology Applications

We have used the ring resonator sensors for biosensing using Human Factor IX and its corresponding antibody⁵⁹ and verify that the devices are able to sense both the protein attachment during functionalization and the protein-antibody binding reaction. The silicon photonic sample preparation begins by cleaning it in a Piranha solution at 80°C for 20 min, then removing the Si native oxide on top of the waveguides using a hydrofluoric acid etchant for 20s. The samples were then thoroughly rinsed in DI water, activated in an air plasma, and incubated in a 1% APTMS solution (94% Ethanol, 5% DI water, APTMS (97%, Sigma-Aldrich)) for 3h. The Human Factor IX was covalently attached with a NHS/EDC chemistry to the amine group of the APTMS linker molecule (0.1 M N-Hydroxysuccinimide, NHS and 0.4 M 1-Ethyl-3-(3-dimethylaminopropyl)carbodiimide, EDC, in equal parts, and 500 $\mu\text{g}/\text{mL}$ Human Factor IX). The different deposition steps were characterized by X-ray photoelectron spectroscopy (XPS) and ellipsometry. The thickness of the APTMS was approximately 8 Å and the thickness of the protein layer was approximately 4 nm. The PDMS microfluidic channels were then aligned and reversibly bonded to the SOI substrate as described in Section 2.1.

The resonance peak shift is then monitored as a function of time, Fig. 10 while functionalizing the racetrack with the protein Human Factor IX in a Phosphate buffered saline (PBS) solution. The position of the resonance peak corresponding to the racetrack in the control channel (which remained filled with PBS) is also monitored as a function of time in order to quantify measurement noise and thermal drift (3σ variation of 2.8 pm). The initial larger shift is caused by a combined effect of a bulk refractive index change of the protein solution and the deposition of a protein layer on top of the waveguide. After switching back to PBS, $\Delta\lambda_p$ is then a measurement of the mass change on the waveguides surface.

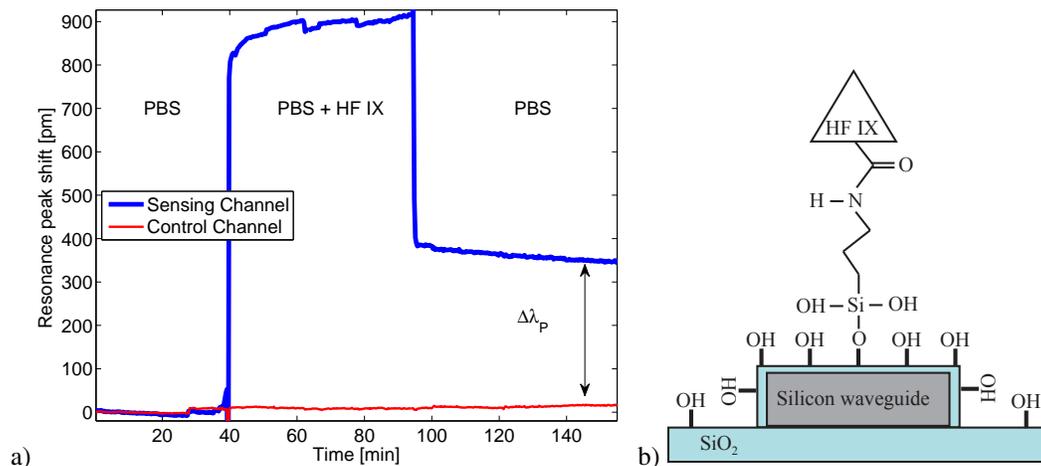


Figure 10. a) Ring resonator resonance peak shift during attachment of the protein Human Factor IX (56 kDa, 500 $\mu\text{g}/\text{mL}$). The values for both the sensing (blue) and control (red) channels are plotted. The difference in peak location ($\Delta\lambda_p$) before and after (both in PBS) is a measurement of the mass change due to the adsorption of the HF IX protein on the sensor. b) Diagram of the attached molecules on the silicon waveguide.

4. CONCLUSION

Sensors operating in aqueous media are fundamentally limited by the optical absorption of water. In the cases where the water (or other sensing media) absorption is dominant, all sensor geometries (ring resonators based on strip or slot waveguides, disks, Bragg grating cavities, 1D photonic crystals, etc) and light polarizations (TE-like, TM-like) will theoretically offer the same performance in terms of limit of detection. The differences between sensor configurations is important where other loss mechanisms are present, such as waveguide scattering loss, waveguide material absorption, or resonator radiation loss. In these cases, it is important to minimize the ratio of other losses relative to analyte optical absorption losses. In particular, increasing the analyte absorption by resorting to TM modes, and moving the optical field away from the rough waveguide sidewall, improves this ratio and allows the sensor to approach the fundamental limits of detection. The structures that are most amenable to reaching the theoretical limit are in decreasing order: TM waveguides, disks, and TE waveguides. Slot waveguides and 1D photonic crystals are the furthest away from reaching fundamental limits.

Of the sensors surveyed in this work, we find that many silicon photonics sensors are near the fundamental limit of detection. Hence, future sensor development should focus on additional system functionality and ease-of-use, e.g., very large array operation, low-cost point-of-care devices, electronic readout, further improvement in readout sensitivity and noise considerations, etc. Additionally, silicon photonic resonator sensor technology has matured to the point where commercially available systems are available¹⁰ and enable complex biological experimentation research to take place.²⁹ The next steps will be for this technology to move to clinical, hospital, and point-of-care applications.

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